General information

TNC 620

- Compact contouring control for **milling, drilling, and boring machines**
- Axes: 8 control loops, of which up to 2 are configurable as spindles
- For operation with HEIDENHAIN inverter systems and preferably HEIDENHAIN motors
- Uniformly digital with HSCI interface and EnDat interface
- Compact size
- Storage medium: CompactFlash memory card
- Programming in HEIDENHAIN Klartext format or according to ISO
- Standard milling, drilling, and boring cycles
- Touch probe cycles
- Short block processing time (1.5 ms)

Version with touchscreen:

- 19-inch screen (vertical), keyboard, and main computer in one unit (MC 8410)
- Integration of the keyboard in the lower screen area
- Multi-touch operation
- MC 8410 is compatible in its installation dimensions with the MC 7410

Version with operating keys:

- 15-inch screen, keyboard, and main computer in one unit (MC 7410)
- Screen and main computer in one unit (MC 7420) and separate keyboard with integrated ASCII keys

System test

Controls, motors, and encoders from HEIDENHAIN are in most cases integrated as components in larger systems. In these cases, comprehensive tests of the complete system are required, irrespective of the specifications of the individual devices.

Parts subject to wear

Controls from HEIDENHAIN include parts subject to wear, particularly the backup battery and fans.

Standards

Standards (ISO, EN, etc.) apply only where explicitly stated in the brochure.

Note

Microsoft, Windows 7, 8, 10 and Internet Explorer are registered trademarks of Microsoft Corporation. Intel, Intel Core, and Celeron are registered trademarks of Intel Corporation.

Validity

The features and specifications described here apply to the following control and NC software versions:

**TNC 620 with NC software versions**

- 817600-06 (export license required)
- 817601-06 (no export license required)

This brochure supersedes all previous editions, which thereby become invalid. **Subject to change without notice.**

Requirements

Some of these specifications require particular machine configurations. Please also note that, for some functions, a special PLC program must be created by the manufacturer.

Functional safety (FS)

If no explicit distinction is made between standard and FS components (FS = functional safety), then the data and other information apply to both versions (e.g., TE 735, TE 735 FS)
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Please refer to the page references in the tables with the specifications.
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*) For further information, refer to the Inverter Systems for HEIDENHAIN Controls brochure

1) May be necessary depending on the configuration

**Please note:** The MC main computer does not have any PLC inputs/outputs. Therefore one PL 6000, UEC, or UMC is necessary for each control. They feature safety-relevant inputs/outputs as well as the connections for touch probes.
## Accessories

**Accessories**

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<td>• HR 550 FS portable wireless handwheel with display, or</td>
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<td></td>
<td>• TS 460 touch trigger probe with radio and infrared transmission, or</td>
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<td>• TT 460 touch trigger probe with radio and infrared transmission, or</td>
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<td></td>
<td>• Single-station license with virtual keyboard</td>
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<td></td>
<td>• Network license with virtual keyboard</td>
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<td></td>
<td>IPC 6641 – industrial PC for Windows</td>
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</tr>
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<sup>1</sup> Available to registered customers for downloading from the Internet
<sup>2</sup> Available to all customers (without registration) for downloading from the Internet
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## Specifications

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<td>Rotary axes</td>
<td>✓</td>
<td></td>
</tr>
<tr>
<td>Synchronized axes</td>
<td>✓</td>
<td></td>
</tr>
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<td>PLC axes</td>
<td>✓</td>
<td></td>
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<td><strong>Main spindle</strong></td>
<td><strong>Milling:</strong> max. 2; second spindle can be controlled by PLC alternately with the first</td>
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<td>Speed</td>
<td>Maximum of 60 000 rpm (with option 49: max. 120 000 rpm)*</td>
<td>60</td>
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<td>✓</td>
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<td>1.8 GB</td>
<td>15</td>
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<td>0.1 µm, 0.01 µm with option 23</td>
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<td>0.0001*, 0.000001* with option 23</td>
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<tr>
<td>Rotary axes</td>
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<td></td>
<td>No. of motor pole pairs</td>
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<td></td>
<td>Screw pitch (mm)</td>
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<td></td>
<td>at f_{PUL} = 5000 Hz</td>
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* For motors with one pole pair
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<td></td>
<td>Double speed: 0.1 ms (option 49)</td>
<td></td>
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<td>Speed controller</td>
<td>Single speed: 0.2 ms</td>
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<td></td>
<td>Double speed: 0.1 ms (option 49)</td>
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</tr>
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<td></td>
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<tr>
<td></td>
<td>( 3333 \text{ Hz} )</td>
<td>150 µs</td>
</tr>
<tr>
<td></td>
<td>( 4000 \text{ Hz} )</td>
<td>125 µs</td>
</tr>
<tr>
<td></td>
<td>( 5000 \text{ Hz} )</td>
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</tr>
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<td>75 µs with option 49</td>
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<td>( 8000 \text{ Hz with option 49} )</td>
<td>62.5 µs with option 49</td>
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<td>( 10000 \text{ Hz with option 49} )</td>
<td>50 µs with option 49</td>
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<td></td>
<td>In operating panel: 0 °C to 50 °C</td>
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<td>Storage: –20 °C to 60 °C</td>
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**Integrated PLC**

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| Program input at the control | **MC 8410**: Via screen keyboard  
MC 7410: By external USB keyboard  
MC 7420: By TE 7xx | 75 |
| Program input via PC    | ✓ | 75   |
| Symbolic PLC-NC interface | ✓ | 75   |
| PLC memory              | 350 MB         | 75   |
| PLC cycle time          | 9 ms to 30 ms (adjustable) | 75   |

**PLC inputs/outputs**

A PLC system can consist of max. seven PLB 61xx and max. two MB 7xx, one TE 7x5, or one PLB 600x. A total maximum of 1000 inputs/outputs is supported.

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<th>PLC inputs, DC 24 V</th>
<th>Via PL, UEC, UMC</th>
<th>24, 19</th>
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<td>PLC outputs, DC 24 V</td>
<td>Via PL, UEC, UMC</td>
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<td>Analog outputs, ± 10 V</td>
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**PLC functions**

| Small PLC window       | ✓ | 76   |
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| PLC positioning        | ✓ | 76   |
| PLC basic program      | ✓ | 78   |

**Integration of applications**

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<td>2 x 1000BASE-T</td>
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| USB                 | Rear: 4 x USB 3.0
Front: USB 2.0 | 80 |
| V.24/RS-232-C       | ✓ | 80 |

### Protocols

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<tr>
<th><strong>Protocols</strong></th>
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<tbody>
<tr>
<td>Standard data transmission</td>
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<td>Blockwise data transfer</td>
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<td>LSV2</td>
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### Encoder inputs

<table>
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<tr>
<th><strong>Encoder inputs</strong></th>
<th><strong>Position</strong></th>
<th><strong>Incremental</strong></th>
<th><strong>Absolute</strong></th>
<th><strong>Speed</strong></th>
<th><strong>Incremental</strong></th>
<th><strong>Absolute</strong></th>
<th><strong>Nominal-value outputs</strong></th>
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<tr>
<td></td>
<td><strong>UEC 111</strong></td>
<td><strong>UEC 112</strong></td>
<td><strong>UEC 113</strong></td>
<td><strong>UMC 111</strong></td>
<td><strong>CC 6106</strong></td>
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<td>Absolute</td>
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### Nominal-value outputs

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<th><strong>PWM</strong></th>
<th><strong>Motor connections</strong></th>
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# User functions

<table>
<thead>
<tr>
<th>User function</th>
<th>Standard</th>
<th>Option</th>
<th>TNC 620</th>
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<tbody>
<tr>
<td>Short description</td>
<td>✓ 0/1</td>
<td>✓</td>
<td>Basic version: 3 axes plus closed-loop spindle 1st or 2nd additional axis for 4 or 5 axes plus spindle Digital current and speed control</td>
</tr>
<tr>
<td>Program entry</td>
<td>✓</td>
<td>0/1</td>
<td>HEIDENHAIN Klartext Direct loading of contours or machining positions from DXF files and saving as Klartext contouring program or as point table ISO with MC 7410: Soft keys or external USB keyboard; with MC 7420: internal ASCII keyboard</td>
</tr>
<tr>
<td>Position values</td>
<td>✓ ✓ ✓</td>
<td></td>
<td>Nominal positions for lines and arcs in Cartesian coordinates or polar coordinates Incremental or absolute dimensions Display and entry in mm or inches</td>
</tr>
<tr>
<td>Tool compensation</td>
<td>✓ 21</td>
<td>9</td>
<td>Tool radius in the working plane and tool length Radius compensated contour look ahead for up to 99 blocks (M120) Three-dimensional tool-radius compensation for changing tool data without having to recalculate an existing program</td>
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<tr>
<td>Tool tables</td>
<td>✓</td>
<td></td>
<td>Multiple tool tables with any number of tools</td>
</tr>
<tr>
<td>Cutting data</td>
<td>✓</td>
<td></td>
<td>Automatic calculation of spindle speed, cutting speed, feed per tooth, and feed per revolution</td>
</tr>
<tr>
<td>Constant contour speed</td>
<td>✓ ✓ ✓</td>
<td></td>
<td>Relative to the path of the tool center Relative to the tool’s cutting edge</td>
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<tr>
<td>Parallel operation</td>
<td>✓</td>
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<td>Creating a program with graphical support while another program is being run</td>
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<tr>
<td>3-D machining</td>
<td>✓ 9</td>
<td>9</td>
<td>Motion control with smoothed jerk 3-D tool compensation via surface-normal vectors Changing the tilt position with handwheel superimpositioning; maintaining the position of the tool point (TCPM) Keeping the tool normal to the contour Tool radius compensation normal to the tool direction Manual traverse in the active tool-axis system</td>
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<tr>
<td>Rotary table machining</td>
<td>✓ 8</td>
<td>8</td>
<td>Programming of cylindrical contours as if in two axes Feed rate in distance per minute</td>
</tr>
<tr>
<td>Contour elements</td>
<td>✓ ✓ ✓ ✓ ✓</td>
<td></td>
<td>Straight line Chamfer Circular path Circle center Circle radius Tangentially connecting circular arc Corner rounding</td>
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<tr>
<td>Contour approach and departure</td>
<td>✓ ✓ ✓ ✓ ✓</td>
<td></td>
<td>Via straight line: tangential or perpendicular Via circular arc</td>
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<tr>
<td>FK free contour programming</td>
<td>✓ 19</td>
<td></td>
<td>FK free contour programming in HEIDENHAIN Klartext format with graphic support for workpiece drawings not dimensioned for NC</td>
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<tr>
<td>Fixed cycles</td>
<td>✓ 19</td>
<td></td>
<td>Drilling, conventional and rigid tapping, rectangular and circular pockets Peck drilling, reaming, boring, counterboring, centering Milling internal and external threads Clearing level and oblique surfaces Multi-operation machining of straight and circular slots Multi-operation machining of rectangular and circular pockets, and rectangular and circular studs Cartesian and polar point patterns Contour train, contour pocket Contour slot with trochoidal milling Engraving cycle: Engrave text or numbers in a straight line or on an arc OEM cycles (special cycles developed by the machine tool builder) can be integrated</td>
</tr>
<tr>
<td>User function</td>
<td>Standard</td>
<td>TNC 620</td>
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<tr>
<td>-------------------------------------</td>
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<tr>
<td>Program jumps</td>
<td>✓</td>
<td>Subprograms</td>
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</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>Program-section repeats</td>
<td></td>
</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>Calling any program as a subprogram</td>
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<tr>
<td>Coordinate transformation</td>
<td>✓</td>
<td>Shifting, rotating, mirroring, scaling (axis-specific)</td>
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</tr>
<tr>
<td>Chance</td>
<td></td>
<td>Tilting the working plane, PLANE function</td>
<td></td>
</tr>
<tr>
<td>Q parameters Programming with variables</td>
<td>✓</td>
<td>Mathematical functions $=, +, -, \cdot, /$, sin $\alpha$, cos $\alpha$, tan $\alpha$, arc sin, arc cos, arc tan, $a^n$, $e^n$, ln, log, angle $\alpha$ from sin $\alpha$ and cos $\alpha$, square root of $a$, square root of $(a^2 + b^2)$</td>
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</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>Logical operations $=, = /, &lt;, &gt;$</td>
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<tr>
<td>Chance</td>
<td>✓</td>
<td>Calculating with parentheses</td>
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<tr>
<td>Chance</td>
<td>✓</td>
<td>Absolute value of a number, constant $\pi$, negation, truncation of digits before or after the decimal point</td>
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<tr>
<td>Chance</td>
<td>✓</td>
<td>Functions for calculation of circles</td>
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</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>Functions for text processing</td>
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</tr>
<tr>
<td>Programming aids</td>
<td>✓</td>
<td>Calculator</td>
<td></td>
</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>Complete list of all current error messages</td>
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</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>Context-sensitive help function for error messages</td>
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</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>TNCguide: the integrated help system. User information available directly on the TNC</td>
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<tr>
<td>Chance</td>
<td>✓</td>
<td>Graphical support for programming cycles</td>
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<tr>
<td>Chance</td>
<td>✓</td>
<td>Comment and structure blocks in the NC program</td>
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<tr>
<td>CAD viewer</td>
<td>✓</td>
<td>Display of standardized CAD file formats on the TNC</td>
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<tr>
<td>Teach-In</td>
<td>✓</td>
<td>Actual positions can be transferred directly into the NC program</td>
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<tr>
<td>Test graphics Depictions</td>
<td>20</td>
<td>Graphical simulation before a program run, even while another program is running</td>
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<tr>
<td>Chance</td>
<td>20</td>
<td>Plan view / projection in 3 planes / 3-D view, also in tilted working plane / 3-D line graphics</td>
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</tr>
<tr>
<td>Chance</td>
<td>20</td>
<td>Detail zoom</td>
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</tr>
<tr>
<td>Programming graphics</td>
<td>✓</td>
<td>In Programming and Editing mode, the contours of entered NC blocks are rendered (2-D pencil-trace graphics), even while another program is running</td>
<td></td>
</tr>
<tr>
<td>Program-run graphics</td>
<td>20</td>
<td>Graphical simulation during real-time machining</td>
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</tr>
<tr>
<td>Chance</td>
<td>20</td>
<td>Plan view / projection in 3 planes / 3-D view</td>
<td></td>
</tr>
<tr>
<td>Machining time</td>
<td>✓</td>
<td>Calculation of machining time in the Test Run operating mode</td>
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<tr>
<td>Chance</td>
<td>✓</td>
<td>Display of the current machining time in the Program Run operating modes</td>
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</tr>
<tr>
<td>Returning to the contour</td>
<td>✓</td>
<td>Mid-program startup in any block in the program, returning the tool to the calculated nominal position to continue machining</td>
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</tr>
<tr>
<td>Chance</td>
<td>✓</td>
<td>Program interruption, contour departure and return</td>
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<tr>
<td>Preset management</td>
<td>✓</td>
<td>For saving any reference points</td>
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<tr>
<td>Datum tables</td>
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<td>Multiple datum tables for storing workpiece-specific datums</td>
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<tr>
<td>Pallet tables</td>
<td>22</td>
<td>Workpiece-oriented execution of pallet tables (with any number of entries for the selection of pallets, NC programs, and datums)</td>
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<tr>
<td>Touch probe cycles</td>
<td>17</td>
<td>Calibrating the touch probe</td>
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<tr>
<td>Chance</td>
<td>17</td>
<td>Compensation of workpiece misalignment, manual or automatic</td>
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<tr>
<td>Chance</td>
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<td>Reference-point setting, manual or automatic</td>
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<tr>
<td>Chance</td>
<td>17</td>
<td>Automatic tool and workpiece measurement</td>
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<tr>
<td>User function</td>
<td>Standard</td>
<td>Option</td>
<td>TNC 620</td>
</tr>
<tr>
<td>-------------------------------</td>
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<td>--------</td>
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<tr>
<td>Parallel secondary axes</td>
<td>✓</td>
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<td>Compensation of movement in the secondary axes U, V, W through the principal axes X, Y, Z</td>
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<tr>
<td></td>
<td>✓</td>
<td>✓</td>
<td>Movements of a parallel axis included in the position display of the associated principal axis (sum display)</td>
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<tr>
<td></td>
<td>✓</td>
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<td>Defining the principal and secondary axes in the NC program makes it possible to run programs on different machine configurations</td>
</tr>
<tr>
<td>Conversational languages</td>
<td>✓</td>
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<td>English, German, Czech, French, Italian, Spanish, Portuguese, Dutch, Swedish, Danish, Finnish, Norwegian, Slovenian, Slovak, Polish, Hungarian, Russian (Cyrillic), Romanian, Turkish, Chinese (traditional and simplified), Korean</td>
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## Options

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<tr>
<th>Option number</th>
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<th>Comment</th>
<th>Page</th>
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<tbody>
<tr>
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<td>Additional control loop 1</td>
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<td>Rotary table machining</td>
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<td>• Programming of cylindrical contours as if in two axes</td>
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<td>• 3-D tool compensation via surface normal vectors</td>
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<td>• Using the electronic handwheel to change the angle of the swivel head during program run without affecting the position of the tool point (TCPM = Tool Center Point Management)</td>
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<td>• Keeping the tool normal to the contour</td>
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<td>• Tool radius compensation normal to the tool direction</td>
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<td>• Manual traverse in the active tool-axis system</td>
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<td>Interpolation</td>
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<td>• Linear in more than 4 axes (export license required)</td>
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<td>Touch probe functions</td>
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<td>634063-01</td>
<td>Touch probe cycles</td>
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<td>• Compensation of workpiece misalignment, setting of presets</td>
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<td>• Setting of presets</td>
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<td>• Automatic tool and workpiece measurement</td>
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<td>• Touch probe input enabled for non-HEIDENHAIN systems</td>
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<td>HEIDENHAIN DNC</td>
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<td>Communication with external PC applications over COM component</td>
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<td>19</td>
<td>Advanced programming features</td>
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<td>FK free contour programming</td>
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<td>Fixed cycles</td>
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<td>• Peck drilling, reaming, boring, counterboring, centering</td>
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<td>• Milling internal and external threads</td>
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<td>• Clearing level and oblique surfaces</td>
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<td>• Multi-operation machining of straight and circular slots</td>
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<td>• Multi-operation machining of rectangular and circular pockets</td>
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<td>• Cartesian and polar point patterns</td>
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<td>• Contour train, contour pocket—also with contour-parallel machining</td>
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<td>• Contour slot with trochoidal milling</td>
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<td>• Special cycles developed by the machine tool builder can be integrated</td>
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<tr>
<td>Option number</td>
<td>Option</td>
<td>As of NC software 81760x-</td>
<td>ID</td>
<td>Comment</td>
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<td>Advanced graphic features</td>
<td>01</td>
<td>628253-01</td>
<td>Program-verification graphics, program-run graphics&lt;br&gt;Plan view, view in three planes, 3-D view</td>
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<td>21</td>
<td>Advanced Function Set 3</td>
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<td>628254-01</td>
<td>Tool compensation&lt;br&gt;Radius-compensated contour look-ahead for up to 99 blocks (LOOK AHEAD)&lt;br&gt;3-D machining&lt;br&gt;Superimposing handwheel positioning during program run</td>
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<td>22</td>
<td>Pallet management</td>
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<td>Pallet management</td>
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<td>23</td>
<td>Display step</td>
<td>01</td>
<td>632986-01</td>
<td>Display step to 0.01 µm or 0.000 01°</td>
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<td>24</td>
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<td>01</td>
<td>634621-01</td>
<td>Gantry axes in master-slave torque control</td>
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<td>42</td>
<td>CAD import</td>
<td>05</td>
<td>526450-01</td>
<td>Importing of contours from 2-D and 3-D models, e.g. STEP, IGES, DXF</td>
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<tr>
<td>46</td>
<td>Python OEM process</td>
<td>01</td>
<td>579650-01</td>
<td>Execute Python applications</td>
<td>77</td>
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<td>KinematicsOpt</td>
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<td>630916-01</td>
<td>Touch-probe cycles for the automated measurement of rotary axes</td>
<td>71</td>
</tr>
<tr>
<td>49</td>
<td>Double-speed axes</td>
<td>01</td>
<td>632223-01</td>
<td>Short control-loop cycle times for direct drives</td>
<td>63</td>
</tr>
<tr>
<td>93</td>
<td>Extended tool management</td>
<td>02</td>
<td>676938-01</td>
<td>Extended tool management</td>
<td></td>
</tr>
<tr>
<td>133</td>
<td>Remote Desktop Manager</td>
<td>01</td>
<td>894423-01</td>
<td>Display and remote operation of external computer units (e.g., a Windows PC)</td>
<td>82</td>
</tr>
<tr>
<td>137</td>
<td>State Reporting</td>
<td>06</td>
<td>123224-01</td>
<td>State Reporting Interface (SRI): provision of operating statuses</td>
<td></td>
</tr>
<tr>
<td>141</td>
<td>Cross Talk Comp.</td>
<td>01</td>
<td>800542-01</td>
<td>CTC: Compensation of axis couplings</td>
<td>67</td>
</tr>
<tr>
<td>142</td>
<td>Pos. Adapt. Control</td>
<td>01</td>
<td>800544-01</td>
<td>PAC: Position-dependent adaptation of control parameters</td>
<td>67</td>
</tr>
<tr>
<td>143</td>
<td>Load Adapt. Control</td>
<td>01</td>
<td>800545-01</td>
<td>LAC: Load-dependent adaptation of control parameters</td>
<td>68</td>
</tr>
<tr>
<td>144</td>
<td>Motion adaptive control</td>
<td>01</td>
<td>800546-01</td>
<td>MAC: Motion-dependent adaptation of control parameters</td>
<td>68</td>
</tr>
<tr>
<td>145</td>
<td>Active chatter control</td>
<td>01</td>
<td>800547-01</td>
<td>ACC: Active suppression of chatter</td>
<td>65</td>
</tr>
<tr>
<td>146</td>
<td>Active vibration damping</td>
<td>01</td>
<td>800548-01</td>
<td>AVD: Active vibration damping</td>
<td>67</td>
</tr>
<tr>
<td>154</td>
<td>Batch process manager</td>
<td>05</td>
<td>1219521-01</td>
<td>Planning and executing multiple machining operations</td>
<td>59</td>
</tr>
<tr>
<td>155</td>
<td>Component Monitoring</td>
<td>06</td>
<td>1226833-01</td>
<td>Monitoring for component overloading and wear</td>
<td></td>
</tr>
</tbody>
</table>
**HSCI control components**

**Main computers**

**Main computer**
The **MC 8410** and **MC 74xx** main computers feature:
- Intel Celeron 1047 processor (1.4 GHz, dual-core)
- 2 GB SDRAM main memory
- HSCI interface to the controller unit and to other control components
- USB 2.0 port with cover cap on front

To be ordered separately, and installed in the main computer by the OEM:
- CFR memory card with the NC software
- The **System Identification Key component** (SIK) for enabling control loops and software options

Special features of the **MC 8410**:
- 19-inch screen (vertical), resolution: 1024 x 768 pixels
- Without feed-rate and spindle-speed potentiometers (potentiometers are integrated in the MB 721)
- Multi-touch operation
- ASCII keyboard integrated in the screen
- Software support as of 81760x-04 SP2

Special features of the **MC 74x0**
- 15-inch screen, resolution: 1024 x 768 pixels
- On MC 7410: TNC operating panel with hardware switches; without feed rate and spindle potentiometers (potentiometers are integrated in MB 721)
- On MC 7420: USB port for the TE operating panel

The following HSCI components are necessary for operation of the **TNC 620**:
- MC main computer
- Controller unit
- **PLB 62xx** PLC I/O unit (system PL; integrated in UEC/UMC)
- **MB 721** machine operating panel (integrated in TE 7x5) or **PLB 600x** HSCI adapter for the connection of an OEM machine operating panel

**Interfaces**
The standard main computers feature USB 3.0, RS-232-C/V.24 and Ethernet interfaces for use by the end user. Connection to PROFINET-I/O or PROFIBUS-DP is possible via an additional module.

**Power supply**
Protective Extra Low Voltage (PELV) according to EN 61800-5-1 must be complied with by the power supply for the DC 24 V of the main computer and other HSCI components. It is supplied by the UEC controller unit. If the current consumption is greater than 3.5 A or a CC 6106 is used, then a PSL 130 power supply unit is also necessary.

**Export version**
Because the complete NC software is saved on the CFR storage medium, no export version is required for the main computer itself. Export versions are available only for the easily replaceable storage medium and the SIK component.
Versions

The MC 8410 and MC 74xx main computers are designed for direct installation in the operating panel. There are various versions:

- **Integrated keyboard, touchscreen**
  The MC 8410 features a 19” screen (vertical) with TNC keyboard and ASCII keyboard integrated in the screen.

- **Integrated keyboard, operating keys**
  The MC 7410 main computer includes a 15-inch screen and TNC keyboard.

- **Separate keyboard**
  The MC 7420 main computer features a 15” screen without TNC keyboard. A separate 15” TNC keyboard is required. Hence, the complete ASCII character set is available.

The MC 8410 main computer is supported by NC software 81760x-04 SP2 or later. The MC 74x0 main computer is supported by NC software 81760x-01 or later. These MCs cannot be run on earlier software versions.

The main computers feature the HEROS 5 operating system. Connection of the fieldbus systems is possible selectively via an appropriate additional module.

<table>
<thead>
<tr>
<th>Keyboard</th>
<th>Power consumption</th>
<th>Mass</th>
<th>SIK number</th>
</tr>
</thead>
<tbody>
<tr>
<td>MC 7410</td>
<td>Integrated</td>
<td>52 W</td>
<td>7.8 kg</td>
</tr>
<tr>
<td>MC 7420</td>
<td>Separate</td>
<td>52 W</td>
<td>6.5 kg</td>
</tr>
<tr>
<td>MC 8410</td>
<td>Integrated, touchscreen</td>
<td>52 W</td>
<td>8.6 kg</td>
</tr>
</tbody>
</table>

Options

The capabilities of the TNC 620 can also be adapted at a later time with options to meet new requirements. These options are described on page 13. They are enabled by entering keywords based on the SIK number and are saved in the SIK component. Please provide your SIK number when ordering new options.

Memory medium

The storage medium is a CFR (= CompactFlash Removable) compact flash memory card. It contains the NC software and is used to store NC and PLC programs. The storage medium is removable and must be ordered separately from the main computer.

This CFR uses the fast SATA protocol (CFast). This CRF is compatible with the MCs described in the Main computers section.

- **CFR CompactFlash** 8 GB
  - Free capacity for NC programs: 1.8 GB
  - Free capacity for PLC programs: 350 MB
  - Export license required: ID 1069906-06
  - No export license required: ID 1069906-56

SIK component

The SIK component contains the **NC software license** for enabling control loops and software options. It provides the main computer with an unambiguous ID code—the SIK number. The SIK component is ordered and shipped separately. It must be inserted into a special slot in the MC main computer.

The SIK component with the NC software license is available in various versions, depending on the enabled control loops and options. Additional control loops (up to 6) can be enabled later by entering a keyword. HEIDENHAIN provides the keyword, which is based on the SIK number.
When ordering, please provide the SIK number of your control. When the keywords are entered in the control, they are saved in the SIK component. This enables and activates the options. Should servicing become necessary, the SIK component must be inserted into the replacement control in order to enable all of the required options.

**Master keyword (general key)**

For the commissioning of the TNC 620, there is a master keyword (general key) that enables all options for a single 90-day period. After this period, only those options with the correct keywords will be active. The general key is activated via a soft key.

**TNCkeygen (accessory)**

TNCkeygen is a collection of PC software tools for generating enabling keys for HEIDENHAIN controls for a limited period of time.

With **OEM Key Generator**, you can generate enabling keys for software options by entering the SIK number, the option to be enabled, the duration, and a manufacturer-specific password. The enabling period is limited to 10 to 90 days. Each option can be enabled only once. This option enabling is independent of the general key.

The **OEM daily key generator** generates an enabling key for the protected OEM area. The operator is thereby given access to the area on the day the key was generated.

**NC software license and enabling of control loops**

<table>
<thead>
<tr>
<th>Control loops</th>
<th>Without option</th>
<th>Incl. options 19 and 20</th>
<th>Incl. options 17, 19 and 20</th>
<th>Incl. options 19, 20 and 46</th>
<th>Incl. options 8, 19 and 20</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>4</strong></td>
<td>ID 526924-01</td>
<td>ID 526924-04</td>
<td>ID 526924-20</td>
<td>ID 526924-11</td>
<td>ID 526924-18</td>
</tr>
<tr>
<td></td>
<td>ID 526924-51</td>
<td>ID 526924-54</td>
<td>ID 526924-70</td>
<td>ID 526924-61</td>
<td>ID 526924-68</td>
</tr>
<tr>
<td><strong>5</strong></td>
<td>ID 526924-02</td>
<td>ID 526924-05</td>
<td>-</td>
<td>ID 526924-12</td>
<td>ID 526924-13</td>
</tr>
<tr>
<td></td>
<td>ID 526924-52</td>
<td>ID 526924-55</td>
<td>-</td>
<td>ID 526924-62</td>
<td>ID 526924-63</td>
</tr>
<tr>
<td><strong>6</strong></td>
<td>ID 526924-03</td>
<td>ID 526924-06</td>
<td>-</td>
<td>ID 526924-19</td>
<td>ID 526924-07</td>
</tr>
<tr>
<td></td>
<td>ID 526924-53</td>
<td>ID 526924-56</td>
<td>-</td>
<td>ID 526924-69</td>
<td>ID 526924-57</td>
</tr>
</tbody>
</table>

( Italics: Export version)

**Enabling further control loops**

Further control loops can be enabled individually. Up to **8 control loops** are possible.

<table>
<thead>
<tr>
<th>Individual control loops</th>
<th>Option</th>
</tr>
</thead>
<tbody>
<tr>
<td>1st additional control loop</td>
<td>0</td>
</tr>
<tr>
<td>2nd additional control loop</td>
<td>1</td>
</tr>
</tbody>
</table>

ID 354540-01
ID 353904-01
Controller unit

Due to the very short cycle times of the position, speed, and current controllers, the controller units from HEIDENHAIN are equally suited for conventional drives, for direct drives (linear motors, torque motors), and for HSC spindles. They permit a high loop gain and short reaction times to changing machining forces, and so make the high contour accuracy and surface quality of the workpiece possible.

Single speed control loops are usually sufficient for linear or torque motors and for conventional axes. Double-speed control loops are preferred for HSC spindles and axes that are difficult to control (option 49). In the default setting, all axes are set to single speed. Each axis that is switched from single speed to double speed can reduce the number of available control loops by one. At a PWM frequency greater than 5 kHz, double speed is always required. This requires option 49 to be enabled.

<table>
<thead>
<tr>
<th>Cycle times</th>
<th>At f_PWM</th>
<th>Current controller</th>
<th>Speed controller</th>
<th>Position controller</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Single-speed</td>
<td>Double-speed</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3333 Hz</td>
<td>150 µs</td>
<td>300 µs</td>
<td>150 µs</td>
<td>Same as speed controller</td>
</tr>
<tr>
<td>4000 Hz</td>
<td>125 µs</td>
<td>250 µs</td>
<td>125 µs</td>
<td></td>
</tr>
<tr>
<td>5000 Hz</td>
<td>100 µs</td>
<td>200 µs</td>
<td>100 µs</td>
<td></td>
</tr>
<tr>
<td>6666 Hz(1))</td>
<td>75 µs</td>
<td>150 µs</td>
<td>150 µs</td>
<td></td>
</tr>
<tr>
<td>8000 Hz(1))</td>
<td>60 µs</td>
<td>125 µs</td>
<td>125 µs</td>
<td></td>
</tr>
<tr>
<td>10 000 Hz(1))</td>
<td>50 µs</td>
<td>100 µs</td>
<td>100 µs</td>
<td></td>
</tr>
</tbody>
</table>

\(1)\) Possible only with option 49

The number of enabled control loops depends on the SIK (see Main computers), or on additionally enabled control loops, which can also be ordered as needed later.

versions

- Modular CC 61xx controller units with PWM interface to the inverters
- Compact UEC/UMC inverters with integrated controller unit

Controller units, main computers, and inverters operate in any desired combination.
The CC 6106 controller unit includes:
- Position controller, speed controller, current controller
- HSCI interfaces
- PWM interfaces to the UM, UR, UE power modules
- Interfaces to the speed and position encoders
- Interfaces for power supply (via inverter)
- SPI interfaces for expansion modules (e.g., CMA-H)

<table>
<thead>
<tr>
<th>CC 6106</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Digital control loops</td>
<td>Max. 6 (single speed)</td>
</tr>
<tr>
<td>Speed inputs</td>
<td>6 x 1 Vpp or EnDat 2.2</td>
</tr>
<tr>
<td>Position inputs</td>
<td>6 x 1 Vpp or EnDat 2.2</td>
</tr>
<tr>
<td>PWM outputs</td>
<td>6</td>
</tr>
<tr>
<td>Power consumption (without encoders)</td>
<td>25 W</td>
</tr>
<tr>
<td>Mass</td>
<td>4.1 kg</td>
</tr>
</tbody>
</table>

The UEC 11x compact inverters not only include the inverter, but also a controller with PLC inputs and outputs and an integrated braking resistor. They form a complete solution for machines with a limited number of axes and low power demands.

Controllers
- Position controller, speed controller, current controller
- HSCI interface
- Interfaces to the speed and position encoders
- SPI interface

Inverters
- Power electronics
- Connections for axis motors and spindle motor
- Braking resistor
- Connections for motor holding brakes
- Additional DC-link connection on the front for connection of a PSL 130

System PL (without EnDat support)
- Interfaces for one workpiece touch probe and one tool touch probe
- Integrated PLC (expandable with PL 61xx)
  * UEC 11x: 38 free inputs, 23 free outputs (7 of which can be switched off)
- Configuration with IOconfig PC software
Controllers
4/5/6 digital control loops

Speed inputs
4/5/6 x 1 VPP or EnDat 2.2

Position inputs
4/5/6 x 1 VPP or EnDat 2.2

Inverters
2/3/4 axes
1 axis
Spindle

<table>
<thead>
<tr>
<th>Rated current I_N</th>
<th>Maximum current I_max</th>
<th>at a PWM frequency of</th>
</tr>
</thead>
<tbody>
<tr>
<td>3333 Hz</td>
<td>6.0/12.0 A</td>
<td>9.0/18.0 A</td>
</tr>
<tr>
<td>4000 Hz</td>
<td>5.5/11.0 A</td>
<td>8.3/16.5 A</td>
</tr>
<tr>
<td>5000 Hz</td>
<td>5.0/10.0 A</td>
<td>7.5/15.0 A</td>
</tr>
<tr>
<td>6666 Hz</td>
<td>4.2/8.4 A</td>
<td>6.3/12.6 A</td>
</tr>
<tr>
<td>8000 Hz</td>
<td>3.6/7.3 A</td>
<td>5.5/11.0 A</td>
</tr>
<tr>
<td>10 000 Hz</td>
<td>3.0/6.0 A</td>
<td>4.6/9.2 A</td>
</tr>
</tbody>
</table>

Supply voltage
3AC 400 V (± 10 %); 50 Hz or 3AC 480 V (+6 %/–10 %); 60 Hz

Rated power of DC link
14 kW

Peak power<sup>2</sup> of DC link
18 kW / 25 kW

Power loss at I_N
≈ 450 W

DC-link voltage
DC 565 V

Integral braking resistance<sup>3</sup>
2.1 kW / 27 kW

Power supply unit for HSCI components
DC 24 V / 3.5 A

Module width
160 mm

Mass
≈ 14 kg

Functional safety (FS)
- ✓

UEC 111
ID 1081002-xx

UEC 112
ID 1081003-xx

UEC 113
ID 828471-xx

ID 1075825-xx

ID 1075826-xx

ID 1038694-xx

<sup>1</sup> Axis: 0.2 s cyclic duration factor for cycle duration of 10 s with 70 % rated current preload
Spindle: 10 s cyclic duration factor for cycle duration of 60 s with 70 % rated current preload

<sup>2</sup> 1st value: 40 % cyclic duration factor for cycle duration of 10 min (S6-40 %)
2nd value: 4 s cyclic duration factor for cycle duration of 20 s

<sup>3</sup> 1st value: Continuous power
2nd value: Peak power (1.5 % cyclic duration factor for cycle duration of 120 s)
UMC 11x FS

The UMC 111 FS is a compact inverter with integrated controller unit and PLC inputs/outputs. As opposed to the UEC, it is used exclusively for controlling axis motors and is powered by an external DC link. The UMC automatically enables the control loops needed for auxiliary axes. Further options are unnecessary.

Please note: The UMC does not expand the number of possible axes. Interpolation with NC axes is not possible.

Controllers
- Position controller, speed controller, current controller
- HSCI interface
- Interfaces to the speed encoders
- SPI interface

Inverters
- Power electronics
- Connections for axis motors
- Connections for motor holding brakes

System PL (without EnDat support)
- Integrated PLC, expandable with PL 61xx
  UMC 111 FS: 38 free inputs, 28 free outputs (7 of which can be switched off)
  8 FS inputs, 8 FS outputs
- Configuration with IOcoonfig PC software

| UMC 111 FS |
|------------------|-----------------|
| Controllers | 4 digital control loops |
| Speed inputs | 4 x 1 V_pp or EnDat 2.2 |
| Inverters | 4 axes |
| Rated current \(I_N\)/ Maximum current \(I_{max}\)\(^1\) at a PWM frequency of |
| 3333 Hz | 9.0/18.0 A |
| 4000 Hz | 8.3/16.5 A |
| 5000 Hz | 7.5/15.0 A |
| 6666 Hz | 6.3/12.6 A |
| 8000 Hz | 5.5/11.0 A |
| 10 000 Hz | 4.6/9.2 A |
| Power loss at \(I_N\) | ≈ 300 W |
| DC-link voltage | DC 565 V or DC 650 V |
| 24 V PLC current consumption | DC 24 V / 2 A |
| Module width | 150 mm |
| Mass | ≈ 11 kg |
| UMC 111 FS | ID 664231-xx |

\(^1\) Axis: 0.2 s cyclic duration factor for cycle duration of 10 s with 70 % rated current preload
  Spindle: 10 s cyclic duration factor for cycle duration of 60 s with 70 % rated current preload

The adapter connector makes it possible for applications with purely serial EnDat 2.2 encoders to connect an external KTY or PT 1000 temperature sensor (e.g. of linear and torque motors) and lead it to the speed encoder input of the controller unit.

The adapter connector can also be used in conjunction with encoders with EnDat02 or 1 V_pp interface. The adapter connector is plugged directly onto the speed encoder input (X15 to X20) of the controller unit.
KTY adapter connector  ID 367770-xx
Mass  \( \approx 0.1 \, \text{kg} \)

Additional cables are required for the use of two or more adapter connectors on one controller unit because the connector for an external KTY or PT 1000 temperature sensor does not permit two or more adapter connectors in a row at the CC 61xx.

<table>
<thead>
<tr>
<th>1 m cable</th>
<th>Encoders with EnDat interface (EnDat2.1, EnDat2.2)</th>
<th>Encoders with 1 V_{PP} interface</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>ID 336377-01</td>
<td>ID 312533-01</td>
</tr>
<tr>
<td>3 m cable</td>
<td>ID 336377-03</td>
<td>ID 312533-03</td>
</tr>
</tbody>
</table>
MB 720 machine operating panel

- For MC 7420
- Power supply: DC 24 V/≈ 4 W
- 36 exchangeable snap-on keys with status LED, freely definable via PLC (assignment as per PLC basic program: 12 axis keys, spindle start, spindle stop, 22 further function keys)
- Further operating elements: NC start\(^1\), NC stop\(^1\), emergency-stop key, control voltage On\(^1\), two bore holes for additional keys or keylock switches
- HSCI interface
- MB 720: 7 free PLC inputs and 5 free PLC outputs
  MB 720 FS: 4 free FS inputs and 5 free PLC outputs; additional dual-channel FS inputs for emergency stop and permissive buttons of the handwheel.
- To be able to continue to use the MB 720 (FS) machine operating panel with the MC 7410, the potentiometers on the MC 7410 (ID 1039531-11) must be retrofitted. Use the conversion kit ID 1198759-01.

\(^1\) Keys illuminated, addressable via PLC

<table>
<thead>
<tr>
<th>Model</th>
<th>ID</th>
<th>Mass</th>
</tr>
</thead>
<tbody>
<tr>
<td>MB 720</td>
<td>784803-xx</td>
<td>≈ 1 kg</td>
</tr>
<tr>
<td>MB 720 FS</td>
<td>805474-xx</td>
<td></td>
</tr>
</tbody>
</table>

MB 721 machine operating panel

Same as the MB 720, except:

- Suitable for MC 8410 and MC 7410
- Changed front panel
- Three holes for additional push buttons or keylock switches

<table>
<thead>
<tr>
<th>Model</th>
<th>ID</th>
<th>Mass</th>
</tr>
</thead>
<tbody>
<tr>
<td>MB 721</td>
<td>1164974-xx</td>
<td>≈ 1.6 kg</td>
</tr>
<tr>
<td>MB 721 FS</td>
<td>1164975-xx</td>
<td></td>
</tr>
</tbody>
</table>

TE 730 keyboard

- For MC 7420
- Axis keys
- The keys for axes IV and V are exchangeable snap-on keys.
- Contouring keys
- Operating mode keys
- ASCII keyboard
- Spindle-speed and feed-rate override potentiometer
- USB interface to the MC
- Touchpad

<table>
<thead>
<tr>
<th>Model</th>
<th>ID</th>
<th>Mass</th>
</tr>
</thead>
<tbody>
<tr>
<td>TE 730</td>
<td>805489-xx</td>
<td>≈ 2.4 kg</td>
</tr>
</tbody>
</table>

TE 720 keyboard

Same features as TE 730 but without touchpad

<table>
<thead>
<tr>
<th>Model</th>
<th>ID</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>TE 720</td>
<td>805488-xx</td>
<td></td>
</tr>
</tbody>
</table>

TE 735 keyboard unit with integrated machine operating panel

- For MC 7420
- NC keyboard same as TE 730
- USB interface to the MC main computer
- Machine operating panel (same as MB 720)
- HSCI interface

<table>
<thead>
<tr>
<th>Model</th>
<th>ID</th>
<th>Mass</th>
</tr>
</thead>
<tbody>
<tr>
<td>TE 735</td>
<td>771898-xx</td>
<td>≈ 3.4 kg</td>
</tr>
<tr>
<td>TE 735 FS</td>
<td>805493-xx</td>
<td></td>
</tr>
</tbody>
</table>
PL 6000 PLC input/output systems with HSCI

PL 6000

The PLC inputs and outputs are available via external modular PL 6000 PLC input/output systems. They consist of a basic module and one or more input/output modules. A total maximum of 1000 inputs/outputs is supported. The PL 6000 units are connected to the MC main computer via the HSCI interface. The PL 6000 units are configured with the IOconfig PC software.

Basic modules

There are basic modules with the HSCI interface for 4, 6, or 8 modules. They are mounted on standard NS 35 rails (DIN 46227 or EN 50022).

Supply voltage DC 24 V
Power consumption
- ≈ 48 W at DC 24 V NC
- ≈ 21 W at DC 24 V PLC
Mass 0.36 kg (bare)

1) PLB 6xxx completely filled, incl. TS, TT. For more details regarding power supply for DC 24 V NC, see Power supply for HSCI components.

System PL with EnDat support

- Required once for each control system (except with UEC)
- Connections for TS and TT touch probes
- TS and TT touch probes with EnDat interface are supported
- Safety-relevant inputs/outputs
- Without FS: 12 free inputs, 7 free outputs
  - With FS: 6 free FS inputs, 2 free FS outputs
- Compatible to the system PL
- The slots are fitted with cover strips, so no empty housings are needed
- Software support as of NC software 81760x-05

<table>
<thead>
<tr>
<th>Model</th>
<th>Description</th>
<th>ID</th>
</tr>
</thead>
<tbody>
<tr>
<td>PLB 6204</td>
<td>for 4 I/O modules</td>
<td>1129809-xx</td>
</tr>
<tr>
<td>PLB 6204 FS</td>
<td>for 4 I/O modules</td>
<td>1129808-xx</td>
</tr>
<tr>
<td>PLB 6206</td>
<td>for 6 I/O modules</td>
<td>1129812-xx</td>
</tr>
<tr>
<td>PLB 6206 FS</td>
<td>for 6 I/O modules</td>
<td>1129811-xx</td>
</tr>
<tr>
<td>PLB 6208</td>
<td>for 8 I/O modules</td>
<td>1129813-xx</td>
</tr>
<tr>
<td>PLB 6208 FS</td>
<td>for 8 I/O modules</td>
<td>1129810-xx</td>
</tr>
</tbody>
</table>
## Expansion PL

For connection to the system PL to increase the number of PLC inputs/outputs

<table>
<thead>
<tr>
<th>Model</th>
<th>Description</th>
<th>ID</th>
</tr>
</thead>
<tbody>
<tr>
<td>PLB 6104</td>
<td>for 4 I/O modules</td>
<td>591828-xx</td>
</tr>
<tr>
<td>PLB 6104 FS</td>
<td>for 4 I/O modules</td>
<td>590479-xx</td>
</tr>
<tr>
<td>PLB 6106</td>
<td>for 6 I/O modules</td>
<td>630058-xx</td>
</tr>
<tr>
<td>PLB 6106 FS</td>
<td>for 6 I/O modules</td>
<td>804755-xx</td>
</tr>
<tr>
<td>PLB 6108</td>
<td>for 8 I/O modules</td>
<td>630059-xx</td>
</tr>
<tr>
<td>PLB 6108 FS</td>
<td>for 8 I/O modules</td>
<td>804756-xx</td>
</tr>
</tbody>
</table>

Up to seven PLB 6xxx can be connected to the control.

## I/O modules

There are I/O modules with digital and analog inputs and outputs. For partially occupied basic modules, the unused slots must be occupied by an empty housing.

<table>
<thead>
<tr>
<th>Model</th>
<th>Description</th>
<th>ID</th>
</tr>
</thead>
<tbody>
<tr>
<td>PLD-H 16-08-00</td>
<td>I/O module with 16 digital inputs and 8 digital outputs</td>
<td>594243-xx</td>
</tr>
<tr>
<td>PLD-H 08-16-00</td>
<td>I/O module with 8 digital inputs and 16 digital outputs</td>
<td>650891-xx</td>
</tr>
<tr>
<td>PLD-H 08-04-00 FS</td>
<td>I/O module with 8 digital FS inputs and 4 digital FS outputs</td>
<td>5988905-xx</td>
</tr>
<tr>
<td>PLD-H 04-08-00 FS</td>
<td>I/O module with 4 digital FS inputs and 8 digital FS outputs</td>
<td>727219-xx</td>
</tr>
<tr>
<td>PLD-H 04-04-00 HTLS FS</td>
<td>I/O module with 4 digital FS inputs and 4 high-side/low-side FS outputs</td>
<td>746706-xx</td>
</tr>
</tbody>
</table>

### Power output
Max. 200 W
Mass ≈ 0.2 kg

### Total current
Outputs 0 to 7: ≤ 2 A per output (≤ 8 A simultaneously)

## IOconfig (accessory)

PC software for configuring HSCI and PROFIBUS components
Accessories
Power supply for HSCI components

PSL 13x

HEIDENHAIN offers the PSL 13x power supply unit in order to power the HSCI components. Either line voltage and DC-link voltage or only line voltage is provided to the PSL 13x. The PSL 13x provides the safely separated DC 24 V PELV NC power supply required for the HSCI components by EN 61800-5-1. The NC supply voltage and the PLC supply voltage are separated from each other by basic insulation.

Supply voltage
- PSL 13x (L1, L2): AC 400 V (360 V to 480 V), 50/60 Hz
- PSL 13x (DC-link voltage): DC 400 V to 750 V
- Power consumption ≤1000 W

Outputs NC:
- DC 24 V/≤20 A (double insulation from line power)
- DC 5 V/≤16 A (only for PSL 135) electrically connected with DC 24 V NC
- PLC: DC 24 V/≤20 A (basic insulation from line power)
- Total: ≤32 A/750 W

The PSL 130 serves as a DC 24 V power supply unit for supplying the HSCI components. It is not necessary in connection with the UEC if the total current consumption of the connected HSCI components does not exceed 3.5 A.

<table>
<thead>
<tr>
<th>HSCI components</th>
<th>Current consumption DC 24 V NC</th>
</tr>
</thead>
<tbody>
<tr>
<td>Main computer</td>
<td>MC 7410, MC 7420, MC 8410</td>
</tr>
<tr>
<td>Machine operating panel</td>
<td>PLB 600x MB 7x0</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Keyboard</td>
<td>TE 7x5 (MB integrated)</td>
</tr>
<tr>
<td>PLC inputs/outputs</td>
<td>PLB 62xx PLB 61xx PLD PLA</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Handwheels</td>
<td>HR 520 HRA 551 FS + HR 550 FS</td>
</tr>
<tr>
<td></td>
<td>HR 510 HR 130</td>
</tr>
<tr>
<td></td>
<td>HRA 110 + 3 x HR 150</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Touch probes</td>
<td>See specifications of the touch probes</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Module width</th>
<th>Degree of protection</th>
<th>Mass</th>
<th>ID 575047-xx</th>
</tr>
</thead>
<tbody>
<tr>
<td>PSL 130</td>
<td>50 mm</td>
<td>IP20</td>
<td>2.1 kg</td>
</tr>
</tbody>
</table>

The UV(R) supply units currently available also feature an integrated power supply that provides DC 24 V to HSCI components.
HSCI adapter for OEM machine operating panel

PLB 600x

The PLB 600x HSCI adapter is required in order to connect an OEM-specific machine operating panel to the TNC 620. The spindle-speed and feed-rate override potentiometers of the TE 7xx and the HR handwheel are also connected to these adapters.

- HSCI interface
- Connection for HR handwheel
- Inputs/outputs for keys/key illumination

PLB 6001: Terminals for 72 PLC inputs and 40 PLC outputs
PLB 6001 FS: Terminals for 36 FS inputs and 40 PLC outputs
PLB 6002 FS: Terminals for 4 FS inputs, 64 PLC inputs and 40 PLC outputs

- Screw fastening or top-hat-rail mounting
- Configuration of the PLC inputs/outputs with the IOconfig computer software

PLB 6001 ID 668792-xx
PLB 6001 FS ID 722083-xx
PLB 6002 FS ID 1137000-xx
Mass ≈ 1.2 kg
Additional modules

Overview
The additional modules are directly connected to the HSCI control system through a slot on the MC main computer, on the CC controller unit, or on the UEC or UMC inverter.

Module for analog axes
Digital drive designs sometimes also require analog axes or spindles. The additional module CMA-H 04-04-00 (Controller Module Analog—HSCI) makes it possible to integrate analog servo drives in an HSCI system.

The CMA-H is integrated into the HSCI control system via a slot on the underside of the CC or UEC. Every controller unit has slots for two boards. The CMA-H does not increase the total number of available axes: every analog axis used reduces the number of available digital control loops by one. Analog control loops also need to be enabled on the SIK. The analog control-loop outputs can be accessed only via the NC, not via the PLC.

Additional module for analog axes/spindles:
- Expansion board for CC 61xx or UEC controller units
- 4 analog outputs, ±10 V for axes/spindle
- Spring-type plug-in terminals

CMA-H 04-04-00
ID 688721-xx

Fieldbus systems
An expansion board can be used to provide the TNC 620 with a PROFIBUS or PROFINET interface at any time. The modules are integrated in the control system by using a slot on the MC. This makes the connection to an appropriate fieldbus system as master possible. As of version 3.0, the interface is configured with IOconfig.

PROFIBUS-DP module
Additional module for PROFIBUS-DP:
- Expansion board for the MC main computer
- Connection for 9-pin D-sub connector (female) to X121

PROFIBUS-DP additional module
ID 828539-xx

PROFINET-IO module
Additional module for PROFINET-IO:
- Expansion board for the MC main computer
- RJ45 connection at X621 and X622

PROFINET-IO additional module
ID 828541-xx

Combined PROFIBUS-DP/PROFINET-IO module
Additional module for PROFIBUS-DP and PROFINET-IO:
- Expansion board for the MC main computer
- Connection for RJ45 connector to X621 (PROFINET-IO) and M12 connector to X121 (PROFIBUS-DP)
- Additionally connectable terminating resistor for PROFIBUS-DP with front LED

Additional module for PROFIBUS-DP and PROFINET-IO
ID 1160940-xx
Touch probes

Overview

Touch probes for tool and workpiece measurement are connected via the system PL 62xx or the UEC/UMC. These touch probes generate a trigger signal that saves the current position value to the NC. The EnDat interface makes touch probes intelligent and allows for greater convenience when connecting them to HEIDENHAIN controls. For more information on touch probes, please refer to the Touch Probes for Machine Tools brochure (ID 1113984).

Workpiece measurement

The TS touch trigger probes feature a stylus for probing workpieces. HEIDENHAIN controls feature standard routines for aligning and measuring workpieces, and for setting presets. The touch probes are available with various clamping shanks. Assorted stylus are available as accessories.

Touch probes with **cable connection for signal transmission** for machines with manual tool change:

- **TS 260**
  - TS 260: new generation touch probe for NC machines

Touch probes with **radio and infrared transmission** for machines with an automatic tool changer (for the appropriate transceiver, see page 30):

- **TS 460**
  - New generation touch probe with compact dimensions
    - Hybrid technology: Signal transmission via radio and infrared signals
    - Large transmission range and long operating time
    - Mechanical collision protection and thermal decoupling
    - With EnDat functionality

Touch probes with **infrared transmission** for machines with an automatic tool changer (for the appropriate transceiver, see page 30):

- **TS 642**
  - Activation via switch in taper shank

- **TS 740**
  - High probing accuracy and reproducibility, low probing force
**Tool measurement**

The touch probes for tool measurement from HEIDENHAIN are suited for probing stationary or rotating tools directly on the machine. The TNC 620 features standard cycles for the measurement of tool length and diameter, as well as of individual teeth. The TNC 620 automatically saves the measured tool dimensions in a tool table. It is also possible to measure tool wear between two machining steps. For the next machining operation, the TNC 620 automatically compensates for the tool dimensions or inserts a replacement tool (as when a tool breaks).

With the **TT touch trigger probes**, the disk-shaped probe contact is deflected from its resting position by contact with the stationary or rotating tool, and a trigger signal is transmitted to the TNC 620.

**TT 160**

New generation touch probe; signal transmission to the control over connecting cable

**TT 460**

New generation touch probe, with hybrid technology: signal transmission via radio or infrared beam (see below for the appropriate transceiver unit). Optionally available with EnDat functionality.

**Transceiver**

Radio and infrared communication is established between the TS or TT touch probe and the SE transceiver.

**SE 660** for radio and infrared transmission (hybrid technology);
SE unit for both the TS 460 and TT 460;

**SE 661** for radio and infrared transmission (hybrid technology);
SE for both the TS 460 and TT 460; EnDat functionality for the transmission of the switching status, as well as for diagnostic information and additional data.

**SE 540** for infrared transmission; for installation in the spindle head

**SE 642** for infrared transmission; SE for both the TS and TT

The following combinations are possible:

<table>
<thead>
<tr>
<th></th>
<th>SE 660</th>
<th>SE 661*</th>
<th>SE 540</th>
<th>SE 642</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>TS 460</strong></td>
<td>Radio/infrared</td>
<td></td>
<td>Infrared</td>
<td>Infrared</td>
</tr>
<tr>
<td><strong>TS 642</strong></td>
<td>Infrared</td>
<td>–</td>
<td>Infrared</td>
<td>Infrared</td>
</tr>
<tr>
<td><strong>TS 740</strong></td>
<td>–</td>
<td>Infrared</td>
<td>Infrared</td>
<td>Infrared</td>
</tr>
<tr>
<td><strong>TT 460</strong></td>
<td>Radio/infrared</td>
<td></td>
<td>Infrared</td>
<td>Infrared</td>
</tr>
</tbody>
</table>

* With EnDat interface
Electronic handwheels

Overview

Support for electronic handwheels is standard on the TNC 620:
• One HR 550 FS wireless handwheel, or
• One HR 510 or HR 520 portable handwheel, or
• One HR 130 panel-mounted handwheel, or
• Up to three HR 150 panel-mounted handwheels via HRA 110

It is possible to operate up to five handwheels or handwheel adapters on a single TNC 620:
• One handwheel via the handwheel input of the main computer
• One handwheel each on up to four HSCI machine operating panels or the PLB 600x HSCI adapter

A mixed operation of handwheels with and without display is not possible. Handwheels with functional safety are cross-circuit-proof due to their special permissive-button logic.

HR 510

Portable electronic handwheel with:
• Keys for actual-position capture and the selection of five axes
• Keys for traverse direction and three preset feed rates
• Three keys for machine functions (see below)
• Emergency stop button and two permissive buttons (24 V)
• Magnetic holding pads

All keys are designed as snap-on keys and can be replaced by keys with other symbols (see overview for HR 510 in Snap-on keys for handwheels).

<table>
<thead>
<tr>
<th>Keys</th>
<th>Without detent</th>
<th>With detent</th>
</tr>
</thead>
<tbody>
<tr>
<td>HR 510</td>
<td>NC start/stop, spindle start (for basic PLC program)</td>
<td>ID 1119971-xx ID 1120313-xx</td>
</tr>
<tr>
<td></td>
<td>FCT A, FCT B, FCT C</td>
<td>ID 1099897-xx –</td>
</tr>
<tr>
<td></td>
<td>Spindle right/left/stop</td>
<td>ID 1184691-xx –</td>
</tr>
<tr>
<td>HR 510 FS</td>
<td>NC start/stop, spindle start (for basic PLC program)</td>
<td>ID 1120311-xx ID 1161281-xx</td>
</tr>
<tr>
<td></td>
<td>FCT A, FCT B, FCT C</td>
<td>– ID 1120314-xx</td>
</tr>
<tr>
<td></td>
<td>Spindle start, FCT B, NC start</td>
<td>– ID 1119974-xx</td>
</tr>
</tbody>
</table>

Mass ≈ 0.6 kg
HR 520

Portable electronic handwheel with:
- Display for operating mode, actual position value, programmed feed rate and spindle speed, error messages
- Override potentiometers for feed rate and spindle speed
- Selection of axes via keys or soft keys
- Actual position capture
- NC start/stop
- Spindle on/off
- Keys for continuous traverse of the axes
- Soft keys for machine functions of the machine manufacturer
- Emergency stop button

<table>
<thead>
<tr>
<th>Without detent</th>
<th>With detent</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>HR 520</strong></td>
<td>ID 670302-xx</td>
</tr>
<tr>
<td><strong>HR 520 FS</strong></td>
<td>ID 670304-xx</td>
</tr>
</tbody>
</table>

Mass ≈ 1 kg

Holder for HR 520

For attaching to a machine ID 591065-xx

HR 550 FS

Electronic handwheel with wireless transmission. Display, operating elements, and functions are like those of the HR 520

In addition:
- Functional safety (FS)
- Radio transmission range of up to 20 m (depending on environment)

<table>
<thead>
<tr>
<th>Without detent</th>
<th>With detent</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>HR 550 FS</strong></td>
<td>ID 1200495-xx</td>
</tr>
</tbody>
</table>

Replacement battery

For HR 550 FS ID 623166-xx

HRA 551 FS

Handwheel holder for HR 550 FS
- For docking the HR 550 FS onto the machine
- Integrated battery charger for HR 550 FS
- Connections to the control and the machine
- Integrated transceiver
- HR 550 FS magnetically held to front of HRA 551 FS

**HRA 551 FS**

<table>
<thead>
<tr>
<th>Without detent</th>
<th>With detent</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>HRA 551 FS</strong></td>
<td>ID 1119052-xx</td>
</tr>
</tbody>
</table>

Mass ≈ 1.0 kg

For more information, see the HR 550 FS Product Information sheet.
## Connecting cables

<table>
<thead>
<tr>
<th></th>
<th>HR 510</th>
<th>HR 510 FS</th>
<th>HR 520</th>
<th>HR 520 FS</th>
<th>HR 550 FS with HRA 551 FS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connecting cable (spiral cable) to HR (3 m)</td>
<td>–</td>
<td>–</td>
<td>✓</td>
<td>✓</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td>✓</td>
<td>✓</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Connecting cable with metal armor</td>
<td>–</td>
<td>–</td>
<td>✓</td>
<td>✓</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td>✓</td>
<td>✓</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Connecting cable without metal armor</td>
<td>–</td>
<td>–</td>
<td>✓</td>
<td>✓</td>
<td>✓ (max. 2 m)</td>
</tr>
<tr>
<td></td>
<td>✓</td>
<td>✓</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Adapter cable for HR/HRA to MC, straight connector</td>
<td>✓</td>
<td>✓</td>
<td>✓</td>
<td>✓</td>
<td>✓ 1)</td>
</tr>
<tr>
<td>Adapter cable for HR/HRA to MC, angled connector (1 m)</td>
<td>✓</td>
<td>✓</td>
<td>✓</td>
<td>✓</td>
<td>✓ 1)</td>
</tr>
<tr>
<td>Extension cable to adapter cable</td>
<td>✓</td>
<td>✓</td>
<td>✓</td>
<td>✓</td>
<td>✓ 1)</td>
</tr>
<tr>
<td>Adapter cable for HRA to MC</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>✓ 2)</td>
</tr>
<tr>
<td>Extension cable to adapter cable</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>–</td>
<td>✓ 2)</td>
</tr>
<tr>
<td>Adapter connector for handwheels without functional safety</td>
<td>✓</td>
<td>✓</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
<tr>
<td>Adapter connector for handwheels with functional safety</td>
<td>–</td>
<td>✓</td>
<td>–</td>
<td>✓</td>
<td>✓</td>
</tr>
</tbody>
</table>

1) For maximum cable lengths up to 20 m between the MB and HRA 551 FS
2) For maximum cable lengths up to 50 m between the MB and HRA 551 FS

See also Cable overview on Page 43.

### HR 130
Panel-mounted handwheel with ergonomic control knob. It is attached to the MB 7x0 or the TE 7x5 either directly or via an extension cable.

<table>
<thead>
<tr>
<th>HR 130</th>
<th>Without detent</th>
<th>With detent</th>
<th>ID 540940-03</th>
<th>ID 540940-01</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mass</td>
<td></td>
<td></td>
<td>≈ 0.7 kg</td>
<td></td>
</tr>
</tbody>
</table>

![HR 130](image)

### HR 150
Panel-mounted handwheel with ergonomic control knob for connection to the HRA 110 handwheel adapter.

<table>
<thead>
<tr>
<th>HR 150</th>
<th>Without detent</th>
<th>With detent</th>
<th>ID 540940-07</th>
<th>ID 540940-06</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mass</td>
<td></td>
<td></td>
<td>≈ 0.7 kg</td>
<td></td>
</tr>
</tbody>
</table>

![HR 150](image)
HRA 110 Handwheel adapter for connection of up to three HR 150 panel-mounted handwheels and two step switches for axis selection and configuration of the subdivision factor. The first and second handwheels are assigned to axes 1 and 2. The third handwheel is assigned to the axes via a step switch or via machine parameters. The position of the second step switch is evaluated over the PLC (e.g., to select the subdivision factor).

**HRA 110**

<table>
<thead>
<tr>
<th>Property</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mass</td>
<td>1.5 kg</td>
</tr>
</tbody>
</table>

ID 261097-xx
Industrial PC

**Additional operating station**

The additional ITC operating stations (Industrial Thin Clients) from HEIDENHAIN are convenient solutions for the additional, decentralized operation of the machine or of machine units such as tool-changing stations. The remote operation strategy, which is tailored to the TNC 620, makes it very easy to connect the ITC over a standard Ethernet connection with a cable length of up to 100 m.

Connecting an ITC is very easy: As soon as the TNC 620 identifies an ITC, it provides it with a current operating system. After the ITC has been started, the complete content of the main screen is mirrored to the ITC’s screen. As a result of this plug&play principle, no configuration by the machine tool builder is necessary. With the standard configuration of the Ethernet interface at X116, the TNC 620 integrates the ITC into the system fully self-sufficiently.

**With touchscreen**

The **ITC 755** is a compact additional operating station for control systems with a 15-inch or 19-inch main screen. Along with the ASCII keyboard and touchscreen it also has the most important function keys of the TNC 620. The ITC 755 adjusts its resolution automatically to fit the size of the main screen. The soft keys are pressed on the touchscreen.

**ITC 755**

ID 1039527-xx

**With operating keys**

The **ITC 750** (15-inch screen) and the TE 73x keyboard unit (to be ordered separately) together comprise a complete second operating system.

**ITC 750** with 15" screen for ID 1039544-xx

TE 73x

**IPC 6641 for Windows**

With the IPC 6641 industrial PC you can start and remotely operate Windows-based applications via the TNC 620’s user interface. The user interface is displayed on the control screen. Option 133 is required for this.

Since Windows runs on the industrial PC, Windows has no effect on the NC machining process. The IPC is connected to the NC main computer via Ethernet. No second screen is necessary, since the Windows applications are displayed on the TNC 620’s screen via remote accesses.

In addition to the IPC 6641 industrial PC, a separately ordered hard disk is required for operation. The operating systems Windows 7, 8, or 10 can be installed on this empty data medium.

**IPC 6641**

With 8 GB of RAM ID 1039543-01

With 16 GB ID 1039543-02

To be installed in Electrical cabinet

Processor Intel Core i7-3 2.1 GHz, quad-core

Mass 4.0 kg

**HDR hard disk**

Empty data carrier for Windows OS

Free capacity ≈ 160 GB
Controlling of auxiliary axes

**PNC 610**

The PNC 610 auxiliary axis control is designed for controlling PLC axes independently of the TNC 620. The PNC 610 does not have an NC channel and thus cannot perform interpolating NC movements. With the IPC auxiliary computer, SIK, and CFR storage medium, the PNC 610 is a separate HSCI system, which can be expanded with HEIDENHAIN inverters. The standard PNC 610 features enabling for six PLC axes.

The system’s design is identical to that of the TNC 620. All relevant HEIDENHAIN tools and a basic program can be used. The position information can be transmitted over PROFIBUS DP (optional), PROFINET IO (optional), or TCP/IP (integrated, system is not capable of real-time), regardless of the platform.

**Auxiliary computer**

The IPC auxiliary computer features the following:

- Processor
- RAM memory
- HSCI interface to the CC 6xxx or UEC controller unit and to other control components
- USB 3.0 interface

The following components must be ordered separately by the OEM and installed in the auxiliary computer:

- CFR CompactFlash memory card with the NC software
- System Identification Key component (SIK) for enabling software options

The following HSCI components are required for operation of the TNC 620:

- IPC auxiliary computer
- Controller unit
- PLB 62xx PLC input/output unit (system PL; integrated in UEC/UMC)

**Interfaces**

The MC offers the end user USB 3.0, V.24/RS-232-C, and Ethernet interfaces. Connection to PROFINET IO or PROFIBUS-DP is possible through an additional module.

**Power supply**

The DC 24 V power supply of the auxiliary computer and other HSCI components is provided through the PSL 13x supply unit with a supply voltage of 24 V-NC, or through the power supply of a UEC compact inverter. For the entire HSCI system, this DC 24 V-NC supply voltage is required to be safely separated voltage (PELV). It must not be connected to the DC 24 V supply voltage for PLC components (e.g., holding brakes).
Design
IPC 6490
To be installed in Electrical cabinet
Processor Intel Celeron Dual Core, 1.4 GHz
RAM memory 2 GB
Power consumption 48 W
Mass 2.3 kg

IPC 8420
Screen 15.6-inch, with touchscreen operation
Installed in Operating panel
Processor Intel Celeron Dual Core, 1.4 GHz
RAM memory 2 GB
Power consumption 48 W
Mass 6.7 kg

Export version
Because the complete NC software is saved on the CFR CompactFlash storage medium, no export version is required for the main computer itself. The NC software of the PNC 610 needs no export license.

Options
The capabilities of the PNC 610 can also be adapted retroactively with options to meet new requirements. Options are enabled by entering keywords based on the SIK number, and are saved in the SIK component. Please indicate your SIK number when ordering new options.

<table>
<thead>
<tr>
<th>Option number</th>
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<th>Remark</th>
<th>Page</th>
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<tr>
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<td>Gantry Axes</td>
<td>ID 634621-01</td>
<td>Gantry axes in master-slave torque control</td>
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<td>46</td>
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<td>ID 579650-01</td>
<td>Execute Python applications</td>
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<td>Synchronizing Functions</td>
<td>ID 1085731-01</td>
<td>Expanded synchronization of axes and spindles</td>
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<td>Cross Talk Comp.</td>
<td>ID 800542-01</td>
<td>CTC: Compensation of axis couplings</td>
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<tr>
<td>142</td>
<td>Pos. Adapt. Control</td>
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<td>PAC: Position-dependent adaptation of control parameters</td>
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<td>LAC: Load-dependent adaptation of control parameters</td>
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<tr>
<td>144</td>
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<td>ID 800546-01</td>
<td>MAC: Motion-dependent adaptation of control parameters</td>
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### Memory medium

The storage medium is a CFR (= CompactFlash Removable) compact flash memory card. It carries the NC software 817591-05. The storage medium is removable and must be ordered separately from the main computer. The NC software is based on the HEIDENHAIN HEROS 5 operating system.

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<td>Free capacity for PLC programs</td>
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### SIK component

The SIK component contains the NC software license for the enabling of software options. It provides the main computer with an unambiguous ID code—the SIK number. The SIK component is ordered and shipped separately. It must be inserted into a special slot in the IPC auxiliary computer. The SIK component of the PNC can enable six axes. The enabling of up to the maximum number of ten axes must be performed via the UMC compact inverter.

<table>
<thead>
<tr>
<th>SIK component for PNC 610</th>
<th>ID 617763-53</th>
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### TNCkeygen (accessory)

TNCkeygen is a collection of PC software tools for generating enabling keys for HEIDENHAIN controls for a limited period of time see "TNCkeygen (accessory)", Page 17.
Snap-on keys for handwheels

Snap-on keys
The snap-on keys make it easy to replace the key symbols. In this way, the HR handwheel can be adapted to different requirements. The snap-on keys are available in packs of five keys.

Overview for HR 520, HR 520 FS, and HR 550 FS

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|                   | ID 330816-61 | ID 330816-77 | ID 330816-82 | ID 330816-88 |
|                   | ID 330816-30 | ID 330816-78 | ID 330816-83 | ID 330816-94 |
|                   | ID 330816-31 | ID 330816-79 | ID 330816-84 | ID 330816-0U |
|                   | ID 330816-32 | ID 330816-80 | ID 330816-89 | ID 330816-91 |
|                   | ID 330816-73 | ID 330816-85 |               |               |

| Spindle functions | ID 330816-68 | ID 330816-69 | ID 330816-08 | ID 330816-48 |
|                  | ID 330816-09 | ID 330816-40 | ID 330816-47 | ID 330816-48 |
|                  | ID 330816-11 | ID 330816-41 | ID 330816-46 | ID 385530-5X |

| Other keys | ID 330816-01 | ID 330816-50 | ID 330816-00 | ID 330816-93 |
|           | ID 330816-61 | ID 330816-33 | ID 330816-27 | ID 330816-0Y |
|           | ID 330816-11 | ID 330816-34 | ID 330816-28 | ID 330816-4M |
|           | ID 330816-12 | ID 330816-13 | ID 330816-29 | ID 330816-3M |
|           | ID 330816-49 | ID 330816-22 | ID 330816-92 | ID 330816-3N |
### Overview for HR 510 and HR 510 FS

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Snap-on keys

The snap-on keys make it easy to replace the key symbols. In this way, the keyboard can be adapted to different requirements. The snap-on keys are available in packs of five keys.

### Overview of control keys

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<td>ID 679843-98</td>
<td>ID 679843-E5</td>
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<tr>
<td></td>
<td>Gray ID 679843-33</td>
<td>ID 679843-42</td>
<td>ID 679843-A7</td>
<td>ID 679843-F2</td>
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<tr>
<td></td>
<td>Red ID 679843-34</td>
<td>ID 679843-45</td>
<td>ID 679843-A8</td>
<td>ID 679843-F4</td>
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<td></td>
<td>Orange ID 679843-35</td>
<td>ID 679843-58</td>
<td>Black ID 679843-D1</td>
<td>Black ID 679843-D2</td>
</tr>
<tr>
<td></td>
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<td>ID 679843-66</td>
<td>ID 679843-D2</td>
<td>ID 679843-D5</td>
</tr>
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<td>ID 679843-37</td>
<td>ID 679843-75</td>
<td>0 ID 679843-D6</td>
<td>ID 679843-F6</td>
</tr>
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<td>ID 679843-38</td>
<td>ID 679843-90</td>
<td>Red ID 679843-D7</td>
<td></td>
</tr>
</tbody>
</table>

### Special keys

Snap-on keys can also be made with special key symbols for special applications. The laser labeling differs in appearance from the labeling of the standard keys. If you need keys for special applications, please consult your contact person at HEIDENHAIN.
Cable overview

Control system with UEC 11x; integrated keyboard

---

**1) Adapter connector for s4810:** for spindle (if necessary)

**2) Only for connection of the KTY PT 1000**

**3) Adapter connector for s46700.02**

**4) Optional for the looping in of KTY**

**5) Adapter connector 544703-01 for spindle (if necessary)**

**6) Only for connection of the KTY PT 1000**

---

**340302-xx**

**323897-xx**

**533631-xx**

**336376-xx**

**60m**

**55m**

**12m**

**298429-xx**

**298430-xx**

**309783-xx**

**310199-xx**

---

**HSCI 722414-xx**

**M12 HSCI 688144-xx**

**X500**

**X501**

**X502**

**MC 7410**

**MC 8410**

**558714-xx**

**max. 30m**

**332115-xx**

**368330-xx**

**533661-xx**

**max. 16m**

**368210-02**

**370226-01**

**383951-01**

**Voltage controller 5 V**

**1 VPP**

**1 V**

**Position inputs**

**Speed inputs**

**EnDat 2.1 interface**

**Axes + spindle:**

**Axes:**

**Voltage controller 5 V**

**12.12.2018**
Control system with CC 6106; integrated keyboard

[Diagram of control system with components labeled]

1) 1m RCN 729
2) X502, X500, X51...X56
3) X500, X501, X502
4) 368210-02, 383951-01
5) 533627-xx, 533661-xx
6) UMCG 11x, X500, X502
7) MC 7410, MC 8410, MB 721
8) HSCI 722414-xx
9) 12.12.2018
Control system with UEC 11x; separate keyboard

... (diagram with various connections and components labeled with numbers and codes)

1) 1m RCN 729
2) 30m RCN 226
3) 55m RCN 228
4) 60m RCN 228

12.12.2018

TE 225 (HS)
2x USB

HSCI 72414-xx M12 HSCI 688144-xx

MC 7420
USB 2.0 354770-xx

USB 1.1 624775-xx

TE 720/TE 730 (FS)
MB 720

X1 X1 X3

TE 225 (HS)
2x USB

HSCI 72414-xx M12 HSCI 688144-xx

MC 7420
USB 2.0 354770-xx

USB 1.1 624775-xx

TE 720/TE 730 (FS)
MB 720

X1 X1 X3

Cabinet

ribbon cable for pots

ribbon cable for sk

ribbon cable for sk

Voltage controller 5 V
368210-02

Voltage controller 5 V
383951-01

adapter connector 544703-01 for spindle (if necessary)

Only for connection of the KTY/PT 1000 with incremental signals

Purely serial EnDat 2.2

Adapter connector 367770-02

Optional for the looping-in of KTY

Included with the MB (0.5m)

Included with the MC (1m)

VL: Extension cable
– for separation points with connecting cable
– for extending existing connecting cable

HSCI total length 70 m

1 VPP

Position inputs

1 VPP

Speed inputs

EnDat 2.1 interface

Axes + spindle:

Voltages: 60 m

Axes: 60 m

Voltage controller 5 V
370226-01

Adapter connector 367770-02

Optional for the looping-in of KTY

Included with the MB (0.5m)

Included with the MC (1m)

8)

7)
Control system with CC 6106; separate keyboard
VL: Extension cable
- for separation points with connecting cable
- for extending existing connecting cable

1) Up to 20m
2) If the total length is >20m: Select the cable ID 663631-xx longer than ID 663631-xx.
**Technical description**

**Digital control design**

**Uniformly digital**

In the uniformly digital control design from HEIDENHAIN, all of the components are connected to each other via purely digital interfaces. The control components are connected via the HEIDENHAIN Serial Controller Interface (HSCI), the HEIDENHAIN real-time protocol for fast Ethernet. The encoders are connected over EnDat 2.2, the bidirectional interface from HEIDENHAIN. A high degree of availability for the entire system, from the main computer to the encoder, is thereby achieved, with the system being diagnosable and immune to noise. The outstanding characteristics of the uniformly digital design from HEIDENHAIN guarantee very high accuracy and surface finish quality, combined with high traversing speeds. For more information, refer to the *Uniformly Digital Technical Information* document.

**HSCI**

HSCI, the HEIDENHAIN Serial Controller Interface, connects the main computer, controller(s), and other control components. The connection between two HSCI components is referred to as an HSCI segment. HSCI is based on 100BaseT Ethernet hardware. A special interface component developed by HEIDENHAIN makes short cycle times for data transfer possible.

**Main advantages of the control design with HSCI:**

- Hardware platform for a flexible and scalable control system (e.g. decentralized axis systems)
- High noise immunity due to digital communication between components
- Hardware basis for implementing “functional safety”
- Simple wiring (commissioning, configuration)
- Inverter connection via the tried-and-tested PWM interface
- Large cable lengths in the entire system (HSCI segment up to max. 70 m)
- High number of possible control loops
- High number of PLC inputs/outputs
- Decentralized arrangement of the controller units

CC or UEC controller units, up to nine PL 6000 PLC I/O modules, and machine operating panels (e.g., MB 72x from HEIDENHAIN) can be connected to the serial HSCI bus of the MC main computer. The HR handwheel is connected directly to the machine operating panel. The combination of monitor and main computer is especially advantageous if the computer is housed in the operating panel. Besides the power supply, all that is then required is an HSCI line to the controller unit in the electrical cabinet.

**Maximum cable lengths for HSCI:**

- For one HSCI segment: 70 m
- For up to 12 HSCI slaves: 290 m (total of HSCI segments)
- For up to 13 HSCI slaves (maximum configuration): 180 m (total of HSCI segments)
The maximum permissible number of individual HSCI participants is listed below.

<table>
<thead>
<tr>
<th>HSCI components</th>
<th>Maximum number</th>
</tr>
</thead>
<tbody>
<tr>
<td>MC/IPC</td>
<td>HSCI master 1 in the system</td>
</tr>
<tr>
<td>CC, UEC, UMC</td>
<td>HSCI slave 4 controller motherboards (distributed to CC, UEC, UMC as desired)</td>
</tr>
<tr>
<td>MB, PLB 600x</td>
<td>HSCI slave 2 in the system</td>
</tr>
<tr>
<td>PLB 61xx, PLB 62xx</td>
<td>HSCI slave 7 in the system</td>
</tr>
<tr>
<td>HR</td>
<td>On MB and/or PLB 600x 5 in the system</td>
</tr>
<tr>
<td>PLD-H-xx-xx-xx FS</td>
<td>In PLB 6xxx FS 10 in the system</td>
</tr>
<tr>
<td>PLD-H-xx-xx-xx, PLA-H-xx-xx-xx</td>
<td>In PLB 6xxx 25 in the system</td>
</tr>
</tbody>
</table>

Total maximum of 1000 inputs/outputs
Control systems with integrated functional safety (FS)

**Basic principle**
With controls featuring integrated functional safety (FS) from HEIDENHAIN, it is possible to attain Safety Integrity Level 2 (SIL 2) in accordance with EN 61508, and Performance Level “d,” Category 3, as per EN ISO 13849-1 (successor standard to EN 954-1). In these standards, the assessment of safety-related systems is based on, among other things, the failure probabilities of integrated components and subsystems. This modular approach aids the manufacturers of safety-related machines in implementing their systems, since they can then build upon prequalified subsystems. This design is taken into account for the TNC 620 control, as well as for safety-related position encoders. Two redundant, mutually independent safety channels form the basis of the controls with functional safety (FS). All safety-relevant signals are captured, processed, and output via two channels. Errors are detected through the mutual comparison of the states and data of both channels. Therefore, the occurrence of a single error in the control does not result in a loss of the safety function.

**Structure**
The safety-related controls from HEIDENHAIN have a dual-channel design with mutual monitoring. The SPLC (safety-related PLC program) and SKERN (safety kernel software) software processes are the basis of the two redundant systems. The two software processes run on the MC main computer (CPU) and CC controller unit components. The dual-channel structure through MC and CC is continued in the PLB 6xxx FS input/output systems and the MB 72x FS. This means that all safety-relevant signals (e.g., permissive buttons and keys, door contacts, emergency stop button) are captured via two channels and are evaluated independently of each other by the MC and CC. The MC and CC use separate channels to also address the power modules and to stop the drives in case of an error.

**Components**
In systems with functional safety, certain hardware components assume safety-relevant tasks. Systems with FS must consist of only those safety-relevant components, including their variants, which HEIDENHAIN has approved for use!

Control components with functional safety are indicated by the suffix “FS” following the model designation (e.g., MB 72x FS).

**MB and TE**
An MB machine operating panel with functional safety (FS) is indispensable for systems with FS. Only on such a machine operating panel do all keys have a dual-channel design. Axes can be moved without additional permissive keys.

**PLB**
In systems with functional safety (FS), a combination of hardware (FS and standard) is possible, but a PLB 62xx FS is mandatory.

**HR**
FS handwheels are required in systems with functional safety because only they have the required cross-circuit-proof permissive buttons.

For a current list of components approved for FS, see the Functional Safety FS Technical Manual.
Safety functions

The following safety functions are integrated into the hardware and software:

- Safe stop reactions (SS0, SS1, and SS2)
- Safe torque off (STO)
- Safe operating stop (SOS)
- Safely limited speed (SLS)
- Safely limited position (SLP)
- Safe brake control (SBC)

Safe operating modes

- Operating mode 1: Automated or production mode
- Operating mode 2: Set-up mode
- Operating mode 3: Manual intervention
- Operating mode 4: Advanced manual intervention, process monitoring

Please note:
The complete feature content is not yet available for all machine types with functional safety (FS). Before planning a machine with functional safety, please inform yourself of whether the current scope of features suffices for your machine design.

Activation of functional safety (FS)

If the control identifies a PLB 62xx FS in the system during booting, functional safety (FS) is activated.

In this case, it is essential that the following prerequisites be fulfilled:

- FS version of safety-relevant control components (e.g. MB 72x FS, TE 735 FS, HR 550 FS)
- Safety-related SPLC program
- Configuration of safe machine parameters
- Wiring of the machine for systems with functional safety

Functional safety (FS) cannot be activated or deactivated by parameter.

For more information on the topic of functional safety (FS), refer to the Technical Information documents Safety-Related Control Technology for Machine Tools and Safety-Related Position Encoders.

For details, see the Functional Safety FS Technical Manual. Your contact person at HEIDENHAIN will be glad to answer any questions concerning controls with functional safety (FS).
Control systems with external safety

**Basic principle**

In control systems without integrated functional safety (FS), no integrated safety functions, such as safe operating modes, safe speed monitoring, or safe operating stop, are available. Such functions must be implemented entirely with the help of external safety components.

Control systems without integrated functional safety (FS) solely support the realization of the safety functions STO (safe torque off: dual-channel interruption of the motor power supply) and SBC (safe brake control: dual-channel triggering of the motor holding brakes). The dual-channel redundancy of the functions must be realized by the OEM through appropriate wiring.
**Operating system**

**HEROS 5**

The TNC 620 and PNC 610 work with the real-time capable HEROS 5 operating system (HEIDENHAIN Realtime Operating System). This future-oriented operating system contains the following powerful functions as part of its standard repertoire:

**Network**
- Network: management of network settings
- Remote Desktop Manager: management of remote applications
- Printer: management of printers
- Shares: management of network shares
- VNC: virtual network computing server

**Safety**
- Portscan (OEM): port scanner
- Firewall: protection against undesired network access
- SELinux: protection against unauthorized changes to system files
- Sandbox: running applications in separated environments

**System**
- Backup/Restore: function for backing-up and restoring the control
- HELogging: evaluation and creation of log files
- Perf2: system monitor
- User administration: define users with different roles and access permissions

**Tools**
- Web browser: Firefox®
- Document Viewer: display PDF, TXT, XLS, and JPEG files
- File Manager: file explorer for managing files and memory media
- Gnumeric: spreadsheet calculations
- Leafpad: text editor for creating notes
- Ristretto: display of image files
- Orage Calendar: simple calendar function
- Screenshot: creation of screendumps
- Totem: media player for playing audio and video files

**User administration**

The improper operation of a control often leads to unplanned machine downtime and costly scrap. The user administration feature can significantly improve process reliability through the systematic avoidance of improper operation. Through the configurable tying of permissions to user roles, access rights can be tailored to the given responsibilities of each operator.

- Logging on to the control with a user account
- User-specific HOME folder for simplified data management
- Role-based access to the control and network data

*Firefox is a registered trademark of the Mozilla Foundation*
Ares

Linear axes
The TNC 620 can control linear axes with any axis designation (X, Y, Z, U, V, W, ...).

Display and programming
-99 999.9999 to +99 999.9999 [mm]
-99 999.9999 to +99 999.9999 [mm] with option 23
Feed rate in mm/min relative to the workpiece contour, or mm per spindle revolution
Feed rate override: 0 % to 150 %

Traverse range
-99 999.9999 to +99 999.9999 [mm]
-99 999.9999 to +99 999.9999 [mm] with option 23
The machine tool builder defines the traverse range. The user can set additional limits to the traverse range if he wishes to reduce the working space. Three different traverse ranges can be defined (selection via PLC).

Rotary axes
The TNC 620 can control rotary axes with any axis designation (A, B, C, U, ...). Special parameters and PLC functions are available for rotary axes with Hirth coupling.

Display and programming
0° to 360° or
-99 999.9999 to +99 999.9999 [°]
-99 999.9999 to +99 999.9999 [°] with option 23
Feed rate in degrees per minute [°/min]

Traverse range
-99 999.9999 to +99 999.9999 [°]
-99 999.9999 to +99 999.9999 [°] with option 23
The machine tool builder defines the traverse range. The user can set additional limits to the traverse range if he wishes to reduce the working space. Various traverse ranges can be defined per axis using parameter sets (selection by PLC).

Free rotation
For milling-turning operations, the rotary axis can be started via the PLC with a defined feed rate. For functions specific to milling/turning machines, see Turning.

Cylinder surface interpolation (option 8)
A contour defined in the working plane is machined on a cylindrical surface.
Tilting the working plane (option 8)

The TNC 620 has special coordinate transformation cycles for controlling swivel heads and tilting tables. The tool lengths and offset of the tilting axes are compensated by the TNC.

The TNC can manage more than one machine configuration (e.g., different swivel heads).

5-axis machining (option 9)

Tool Center Point Management (TCPM)
The offset of the tilting axes is compensated for in a manner such that the position of the tool tip relative to the contour is maintained. Even during machining, handwheel positioning commands can be superimposed such that the tool tip remains on the programmed contour.

Synchronized axes (option 24)

Synchronized axes move in synchronism and are programmed with the same axis designation.

With HEIDENHAIN controls, parallel axis systems (gantry axes) such as on portal-type machines or tilting tables can be moved synchronously to each other through high-accuracy and dynamic position control.

In the case of gantry axes, multiple gantry slave axes can be assigned to a single master axis. They may also be distributed to multiple controller units.

Torque control (option 24)

Torque control is used on machines with mechanically coupled motors, for which

- a defined distribution of drive torque is desired,
- or
- parts of the controlled system show a backlash effect that can be eliminated by “tensioning” the servo drives (e.g. toothed racks).
**Batch Process Manager** (option 154)

Batch Process Manager provides functions for the planning and execution of multiple production jobs on the TNC. It makes it possible to easily edit pallets and to alter the sequence of pending jobs. Moreover, Batch Process Manager performs a look-ahead calculation for all planned jobs or NC programs and informs the operator about whether all of the NC programs can be executed error-free, for example, or whether all necessary tools are available with sufficient service life. Batch Process Manager thereby ensures the smooth execution of the planned jobs. The Batch Process Manager option requires option 93 (Extended Tool Management) and option 22 (Pallet Management) to also be enabled.

**PLC axes**

Axes can be defined as PLC axes. Programming is performed through M functions or OEM cycles. The PLC axes are positioned independently of the NC axes and are therefore designated as asynchronous axes.
Spindle

Overview

The TNC 620 contouring control is used in conjunction with the HEIDENHAIN inverter systems with field-oriented control. As an alternative, an analog nominal speed value can be output.

Controller unit

With the CC controller units and the UEC/UMC inverters, a fundamental PWM frequency can be set for each controller assembly (e.g., 4 kHz). Possible fundamental frequencies are 3.33 kHz, 4 kHz, or 5 kHz. The Double Speed option (option 49) allows this frequency to be increased to up to 16 kHz for high-speed spindles (e.g., for HF spindles). See the Technical Manual.

Controller groups

For example with CC 6106
1: X51 + X52
2: X53 + X54
3: X55 + X56

Maximum spindle speed

The maximum spindle speed is calculated as follows:

\[ n_{\text{max}} = \frac{f_{\text{PWM}}}{60000 \text{ rpm}} \]

\[ f_{\text{PWM}} \text{ = PWM frequency in Hz} \]

\[ NPP \text{ = Number of pole pairs} \]

Operating mode switchover

For controlling the spindle, different parameter sets can be saved for closed-loop control (e.g., for wye or delta connections). You can switch between the parameter sets in the PLC.

Position-controlled spindle

The position of the spindle is monitored by the control.

Encoder

HEIDENHAIN rotary encoder with sinusoidal voltage signals (1 Vpp) or EnDat interface.

Tapping

There are special cycles for tapping with or without floating tap holder. For tapping without floating tap holder, the spindle must be operated under position control.

Spindle orientation

With a position-controlled spindle, the spindle can be positioned exactly to 0.1°.

Spindle override

0 % to 150 %

Gear ranges

A separate nominal speed is defined for each gear range. The gear code is output via the PLC.

Multiple main spindles

Up to two spindles can be controlled alternately. The spindles are switched by the PLC. One control loop is required for each active spindle.
Encoders

Overview
For speed and position control of the axes and spindle, HEIDENHAIN offers both incremental and absolute encoders.

Incremental encoders
Incremental encoders have as their measuring standard a grating consisting of alternating lines and spaces. Relative movement between the scanning head and the scale causes the output of sinusoidal scanning signals. The measured value is calculated by counting the signals.

Reference mark
When the machine is switched on, the machine axes need to traverse a reference mark for an accurate reference to be established between the measured value and the machine position. For encoders with distance-coded reference marks, the maximum travel until automatic reference mark evaluation for linear encoders is only 20 mm or 80 mm, depending on the model, or 10° or 20° for angle encoders.

Evaluation of reference marks
The routine for traversing the reference marks can also be started for specific axes via the PLC during operation (reactivation of parked axes).

Output signals
Incremental encoders with sinusoidal output signals with $\sim 1 \text{ V}_{\text{pp}}$ levels are suitable for connection to HEIDENHAIN numerical controls.

Absolute encoders
With absolute encoders, the position information is contained in several coded tracks. Thus, an absolute reference is available immediately after switch-on. A reference-mark traverse is not necessary. Additional incremental signals are output for highly dynamic control loops.

EnDat interface
The TNC 620 features the serial EnDat 2.2 interface (includes EnDat 2.1) for the connection of absolute encoders.

Note: The EnDat interface on HEIDENHAIN encoders differs in its pin assignment from the interface on Siemens motors with integrated absolute ECN/EQN rotary encoders. Special adapter cables are available.

Encoder inputs
Incremental and absolute linear, angle, or rotary encoders from HEIDENHAIN can be connected to all position encoder inputs of the controller unit.

Incremental and absolute rotary encoders from HEIDENHAIN can be connected to all speed encoder inputs of the controller unit.

<table>
<thead>
<tr>
<th>Inputs</th>
<th>Signal level/Interface$^1\mathbf{)}$</th>
<th>Input frequency$^1\mathbf{)}$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Position</td>
</tr>
<tr>
<td>Incremental signals</td>
<td>$\sim 1 \text{ V}_{\text{pp}}$</td>
<td>33 kHz/350 kHz</td>
</tr>
<tr>
<td></td>
<td>EnDat 2.1</td>
<td></td>
</tr>
<tr>
<td>Absolute position values</td>
<td>EnDat 2.1</td>
<td>–</td>
</tr>
<tr>
<td></td>
<td>EnDat 2.2</td>
<td>–</td>
</tr>
</tbody>
</table>

$^1\mathbf{)}$ Switchable
Digital servo control

**Integrated inverter**
Position controllers, speed controllers, current controllers, and inverters are integrated in the TNC 620. HEIDENHAIN synchronous or asynchronous motors are connected to the TNC 620.

**Axis feedback control**
The TNC 620 can be operated with following error or feedforward control. During roughing operations at high speeds, for example, you can switch to velocity semi-feedforward control via an OEM cycle in order to machine faster at reduced accuracy.

**Operation with following error**
The term “following error” denotes the distance between the momentary nominal position and the actual position of the axis. The velocity is calculated as follows:

\[
\begin{align*}
    v &= k_v \cdot s_a \\
    k_v &= \text{Position loop gain} \\
    s_a &= \text{Following error}
\end{align*}
\]

**Operation with feedforward control**
Feedforward means that a given velocity and acceleration are adapted to the machine. Together with the values calculated from the following error, this given velocity and acceleration becomes the nominal value. A much lower following error thereby manifests itself (in the range of only a few microns).

**Compensation of torque ripples**
The torque of synchronous, torque, and linear motors is subject to periodic oscillations, one cause of which can be permanent magnets. The amplitude of this torque ripple depends on the motor design, and under certain circumstances can have an effect on the workpiece surface. After the axes have been commissioned with the TNCopt software, the Torque Ripple Compensation (TRC) of the CC 61xx or UEC 11x can be used to compensate it.
Control loop cycle times

The cycle time for path interpolation is defined as the time interval during which interpolation points on the path are calculated. The cycle time for fine interpolation is defined as the time interval during which interpolation points are calculated that lie within the interpolation points calculated for path interpolation. The cycle time for the position controller is defined as the time interval during which the actual position value is compared to the calculated nominal position value. The speed controller cycle time is defined as the time interval in which the actual speed value is compared to the calculated nominal speed value. The cycle time for the current controller is defined as the time interval during which the actual value of the electrical current is compared to the calculated nominal value of the electrical current.

CC/UEC/UMC

<table>
<thead>
<tr>
<th></th>
<th>Time (ms)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Path interpolation</td>
<td>3</td>
</tr>
<tr>
<td>Fine interpolation</td>
<td>0.2 ms/0.1 ms (^1) at f(_{PWM}) = 5000 Hz</td>
</tr>
<tr>
<td>Position controller</td>
<td>0.2 ms/0.1 ms (^1) at f(_{PWM}) = 5000 Hz</td>
</tr>
<tr>
<td>Speed controller</td>
<td>0.2 ms/0.1 ms (^1) at f(_{PWM}) = 5000 Hz</td>
</tr>
<tr>
<td>Current controller</td>
<td>0.1 ms at f(_{PWM}) = 5000 Hz</td>
</tr>
</tbody>
</table>

\(^1\) Double speed (with option 49)

Axis clamping

The control loop can be opened through the PLC in order to clamp specific axes.

Double-speed control loops (option 49)

Double-speed control loops permit higher PWM frequencies and shorter cycle times for the speed controller. This enables improved current control for spindles and higher controller performance for linear and torque motors.

Crossover Position Filter (CPF)

To increase the stability of the position control loop in systems with resonances, the position signal from the position encoder, which is filtered through a low-pass filter, is combined with the position signal from the motor speed encoder, which is filtered through a high-pass filter. This signal combination is made available to the position controller as the actual position value. The possible position controller gain (\(k_V\) factor) is increased significantly by this. The filter separation frequency is set specifically for each axis via machine parameters. The CPF can be used only in dual-encoder systems on drive motors with speed and position encoders.
Fast contour milling

**Short block processing time**

The TNC 620 provides the following important features for fast contour machining.

The block processing time of the MC 8410 or MC 7410 is 1.5 ms. This means that the TNC 620 is able to run long programs from the hard disk, even with contours approximated with linear segments as small as 0.2 mm, at a feed rate of up to 8 m/min.

**Look-ahead**

The TNC 620 calculates the geometry ahead of time in order to adjust the feed rate (max. 5000 blocks). In this way, directional changes are detected in time to accelerate or decelerate the appropriate NC axes.

**Jerk**

The derivative of acceleration is referred to as jerk. A linear change in acceleration causes a jerk step. Such motion sequences may cause the machine to oscillate.

**Jerk limiting**

To prevent machine oscillations, the jerk is limited in order to attain optimum path control.

**Smoothed jerk**

The jerk is smoothed by nominal position value filters. The TNC 620 therefore mills smooth surfaces at the highest possible feed rate and yet keeps the contour accurate. The operator programs the permissible tolerance in a cycle. Special filters for HSC machining (HSC filters) can specifically suppress the natural frequencies of an individual machine. The desired accuracy and a very high surface quality are attained.

**Advanced Dynamic Prediction (ADP)**

The Advanced Dynamic Prediction (ADP) function enhances the conventional look-ahead of the permissible maximum feed rate profile, thereby enabling optimized motion control for clean surface finishes and perfect contours. The strengths of ADP are evident, for example, during bidirectional finish milling through symmetrical feed behavior on the forward and reverse paths, as well as through particularly smooth feed rate curves on parallel milling paths. NC programs that are generated on CAM systems have a negative effect on the machining process due to various factors such as short, step-like contours; coarse chord tolerances; and heavily rounded end-point coordinates. Through an improved response to such factors and the exact adherence to dynamic machine parameters, ADP not only improves the surface quality of the workpiece but also optimizes the machining time.
During heavy machining (roughing at high cutting power), strong milling forces arise. Depending on the tool spindle speed, the resonances in the machine tool, and the chip volume (metal-removal rate during milling), the phenomenon known as “chatter” may occur. Chatter subjects the machine to heavy strain and causes ugly marks on the workpiece surface. The tool, too, undergoes heavy and irregular wear due to chatter, even breaking in extreme cases. To reduce chatter tendencies, HEIDENHAIN offers an effective option with its Active Chatter Control (ACC) solution. This option is particularly advantageous during heavy machining. ACC enables substantially higher cutting performance: depending on the machine model, the metal removal rate can be increased by 25% or more. Thus, you can reduce the load on your machine while simultaneously increasing the life of your tools.
The umbrella term Dynamic Precision encompasses a number of HEIDENHAIN milling solutions that significantly improve the dynamic accuracy of a machine tool. The dynamic accuracy of machine tools can be seen in the errors at the tool center point (TCP). The size of these errors depends on the magnitudes of the motion (e.g., speed and acceleration, as well as jerk) and result from the vibrations of the machine components, among other things. Taken together, all of these errors are partially to blame for dimensional errors and faults on the surfaces of workpieces. They therefore have a decisive impact on quality and, in the event of quality-related scrap, on productivity as well.

Because the stiffness of machine tools is limited for reasons of design and economy, problems such as compliance and vibration within the machine design are very difficult to avoid. Dynamic Precision counteracts these problems with intelligent control technology to enable designers to further improve the quality and dynamic performance of machine tools. This saves time and money in production.

The machine tool builder can use the options comprised by Dynamic Precision either individually or in combination:

- **CTC**: Compensates acceleration-dependent position errors at the tool center point, thereby increasing accuracy during acceleration phases
- **AVD**: Active vibration damping improves surfaces
- **PAC**: Position-dependent adaptation of control parameters
- **LAC**: Load-dependent adaptation of control parameters enhances accuracy regardless of load and aging
- **MAC**: Motion-dependent adaptation of control parameters
Cross Talk Compensation (CTC) (option 141)

CTC (option 141) makes it possible to compensate dynamic position errors that are caused by acceleration forces.

To increase productivity, machine tool users are asking for ever higher feed rates and accelerations, while at the same time they need to maintain the highest possible surface quality and accuracy, placing very special requirements on path control.

Highly dynamic acceleration processes introduce forces to the structure of a machine tool. They can deform parts of the machine and thereby lead to deviations at the tool center point (TCP). Besides deformation in the direction of the axis, the dynamic acceleration of an axis due to mechanical axis coupling can also result in the deformation of axes that are perpendicular to the direction of acceleration. The resulting position error at the TCP in the direction of the accelerated axis and lateral axes is proportional to the amount of acceleration.

If the dynamic position error as a function of the axis acceleration is known, this acceleration-dependent error can be compensated with the CTC option (Cross Talk Compensation) in order to prevent negative effects on the surface quality and accuracy of the workpiece. Often, the resulting error at the TCP depends not only on the acceleration but also on the position of the axes in the working space. This can also be compensated by CTC.

Active Vibration Damping (AVD) (option 146)

The high dynamics of modern machine tools lead to deformations in the machine base, frame, and drive train during acceleration and deceleration of the feed drives. This results in vibrations, such as machine setup vibrations, that may reduce the attainable accuracy and surface quality of the workpieces. The Active Vibration Damping (AVD) controller function dampens the especially critical low-frequency oscillations and optimizes the control behavior of the affected axis at the same time so that high-accuracy workpieces with increased surface quality can also be produced at high feed rates. The improved rigidity attained can be used to increase the dynamic limit values (e.g., jerk), and therefore makes reduced machining times possible.

Position Adaptive Control (PAC) (option 142)

PAC (option 142) permits a dynamic and position-dependent adaptation of controller parameters depending on the position of the tool in space.

The specifics of a machine’s kinematics cause a unique position of the axes’ center of gravity in the working space. This results in a variable dynamic behavior of the machine, which can negatively influence the control’s stability depending on the axis positions.

To exploit the potential of the machine’s dynamics, you can use the Position Adaptive Control (PAC) option to change machine parameters based on position. This makes it possible to assign the respective optimal loop gain to defined interpolation points. Additional position-dependent filter parameters can be defined in order to further increase control loop stability.
<table>
<thead>
<tr>
<th>Control Option (option)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Load Adaptive Control (LAC)</strong> (option 143)</td>
<td>LAC (option 143) enables you to adapt controller parameters dynamically depending on the load or friction. The dynamic behavior of machines with rotary tables can vary depending on the mass moment of inertia of the fixed workpiece. The LAC (Load Adaptive Control) option enables the control to automatically ascertain the current workpiece mass moment of inertia as well as current frictional forces. In order to optimize changed control behavior at differing loads, adaptive feedforward controls can exploit data on acceleration, holding torque, static friction, and friction at high shaft speeds.</td>
</tr>
<tr>
<td><strong>Motion Adaptive Control (MAC)</strong> (option 144)</td>
<td>In addition to the position-dependent adaptation of control parameters through the PAC option, the Motion Adaptive Control (MAC) option also provides a means of changing machine parameters based on other input quantities, such as speed, following error, or drive acceleration. Through this motion-dependent adaptation of the control parameters, a speed-dependent adaptation of the $k_v$ factor can be implemented for drive systems whose stability changes due to the different traversing speeds.</td>
</tr>
</tbody>
</table>
Monitoring functions

**Description**

During operation the control monitors the following details:

- Amplitude of the encoder signals
- Edge separation of the encoder signals
- Absolute position from encoders with distance-coded reference marks
- Current position (following error monitoring)
- Actual distance traversed (movement monitoring)
- Position deviation at standstill
- Nominal speed value
- Checksum of safety-related functions
- Supply voltage
- Voltage of the backup battery
- Operating temperature of the MC and CPU
- Run time of the PLC program
- Motor current / motor temperature
- Temperature of the power module
- DC-link voltage

With EnDat 2.2 encoders:

- The CRC checksum of the position value
- EnDat alarm Error1 → EnDat status alarm register (0xEE)
- EnDat alarm Error2
- Edge speed of 5 µs
- Transmission of the absolute position value on the time grid

In the event of hazardous errors, an emergency stop message is sent to the external electronics via the control-is-ready output, and the axes are brought to a stop. The correct connection of the TNC 620 in the machine’s emergency stop loop is checked when the control system is switched on. In the event of an error, the control displays a message in plain language.

**Context-sensitive help**

The HELP and ERR keys provide the user with context-sensitive help. This means that in the event of an error message, the control displays information on the cause of the error and proposes solutions. The machine tool builder can also use this function for PLC error messages.

**KinematicsDesign (accessory)**

KinematicsDesign is a PC program for creating adaptable kinematic configurations. It supports the following:

- Complete kinematic configurations
- Transfer of configuration files between control and PC
- Description of tool-carrier kinematics

Kinematic descriptions created for the iTNC 530 can also be transferred into kinematic descriptions for the TNC 640/620/320/128.

If KinematicsDesign is connected to a control online (operation is also possible with the programming station software), then machine movements can be simulated, and the axes are moved.

The visualization possibilities range from the pure depiction of the transformation chain and a wire model to a depiction of the entire working space.

* No safety functions
Error compensation

Overview
The TNC 620 automatically compensates mechanical errors of the machine.

Linear error
Linear error can be compensated over the entire travel range for each axis.

Nonlinear error
The TNC 620 can compensate for ball-screw pitch errors and sag errors simultaneously. The compensation values are stored in a table. Nonlinear axis-error compensation also makes it possible to compensate for position-dependent backlash.

Backlash
The play between table movement and rotary encoder movement during direction changes can be compensated in length measurements by spindle and rotary encoder. This backlash is outside the controlled system.

Hysteresis
The hysteresis between table movement and motor movement is also compensated in direct length measurements. In this case, the hysteresis is within the controlled system.

Reversal spikes
In circular movements, reversal spikes can occur at quadrant transitions due to mechanical influences. The TNC 620 can compensate for these reversal spikes.

Static friction
At very low feed rates, high static friction can cause the slide to stop and start repeatedly for short periods. This is commonly known as stick-slip. The TNC 620 can compensate for this problematic behavior.

Sliding friction
Sliding friction is compensated for by the speed controller of the TNC 620.

Thermal expansion
To compensate for thermal expansion, the machine’s expansion behavior must be known.

The temperature is ascertained by thermistors connected to the analog inputs of the TNC 620. The PLC evaluates the temperature information and passes the compensation value to the NC.
Using the KinematicsOpt function, machine tool builders or end users can check the accuracy of rotary or swivel axes, and compensate for possible displacements of the center of rotation of these axes. The deviations are automatically transferred to the kinematics description and can be taken into account in the kinematics calculation.

In order to measure the rotary axes, you must attach a calibration sphere (e.g., KKH 100 or KKH 250 from HEIDENHAIN) at any position on the machine table. A HEIDENHAIN touch probe uses a special cycle to probe this calibration sphere, and measures the rotary axes of the machine fully automatically. But first you define the resolution of the measurement and define for each rotary axis the range that you want to measure. The results of measurement are the same regardless of whether the axis is a rotary table, a tilting table, or a swivel head.

HEIDENHAIN offers calibration spheres as accessories for the measurement of rotary axes with KinematicsOpt:

<table>
<thead>
<tr>
<th>Calibration sphere (accessory)</th>
<th>KKH 100</th>
<th>Height: 100 mm</th>
<th>ID 655475-02</th>
</tr>
</thead>
<tbody>
<tr>
<td>KKH 250</td>
<td>Height: 250 mm</td>
<td>ID 655475-01</td>
<td></td>
</tr>
</tbody>
</table>
Commissioning and diagnostic aids

Overview
The TNC 620 provides comprehensive internal commissioning and diagnostic aids. It also includes highly effective PC software for diagnostics, optimization, and remote control.

ConfigDesign (accessory)
PC software for configuring the machine parameters
- Stand-alone machine-parameter editor for the control: all support information, additional data, and input limits are shown for the parameters
- Configuration of machine parameters
- Comparison of parameters from different controls
- Importing of service files: easy testing of machine parameters in the field
- Rule-based creation and management of machine configurations for multiple controls (together with PLCdesign)

DriveDiag
DriveDiag permits quick and easy troubleshooting of the drives. The following diagnostic functions are available:
- Reading and displaying the electronic ID labels of QSY motors with EQN 13xx or ECN 13xx as well as the inverter modules UVR 1xxD and UM 1xxD
- Displaying and evaluating the internal control conditions and the status signals of the inverter components
- Displaying the analog values available to the drive controller
- Automatic test for the proper functioning of motors and inverters, as well as of position and speed encoders

DriveDiag can be called immediately at the control through the diagnostics soft key. End users have read-access, whereas the code number for the machine tool builder gives access to comprehensive testing possibilities with DriveDiag.

Oscilloscope
The TNC 620 features an integrated oscilloscope. Both X/t and X/Y graphs are possible. The following characteristic curves can be recorded and stored in six channels:
- Actual value and nominal value of the axis feed rate
- Contouring feed rate
- Nominal and actual position
- Following error of the position controller
- Nominal and actual values for speed, acceleration, and jerk
- Content of PLC operands
- Encoder signal (0°–A) and (90°–B)
- Difference between position and speed encoder
- Nominal velocity value
- Integral-action component of the nominal current value
- Torque-determining nominal current value

Logic signals
Simultaneous graphic representation of the logic states of up to 16 operands (markers, words, inputs, outputs, counters, timers)
- Marker (M)
- Input (I)
- Output (O)
- Timer (T)
- Counter (C)
- IpoLogic (X)
**TNCopt (accessory)**

PC software for commissioning digital control loops.

Functions (among others):
- Commissioning the current controller
- Commissioning the velocity controller (automatic)
- (Automatic) optimization of sliding-friction compensation
- (Automatic) optimization of compensation for reversal spikes
- Optimization of the $k_v$ factor (automatic)
- Circular interpolation test, contour test

**Online Monitor (OLM)**

The online monitor is a component of the TNC 620 and is called over a code number. It supports commissioning and diagnosis of control components through the following:
- Display of control-internal variables for axes and channels
- Display of controller-internal variables (if a CC is present)
- Display of hardware signal states
- Various trace functions
- Activation of spindle commands
- Enabling of control-internal debug outputs

**TNCscope (accessory)**

PC software for transferring the oscilloscope files to a PC.

With TNCscope you can record and save up to 16 channels simultaneously.

**Note:** The trace files are saved in the TNCscope data format.

**API DATA**

The API DATA function enables the control to display the states or contents of the symbolic API markers and API double words. This function requires that your PLC program use the symbolic memory interface.

**Note:** The API DATA function does not provide usable display values with the iTNC 530-compatible memory interface (API 1.0)

**Table function**

The current conditions of the markers, words, inputs, outputs, counters, and timers are displayed in tables. The conditions can be changed through the keyboard.

**Trace function**

The current content of the operands and the accumulators is shown in the statement list in each line in hexadecimal or decimal code. The active lines of the statement list are marked.

**Log**

For the purpose of error diagnostics, all error messages and keystrokes are recorded in a log. The entries can be read using the PLCdesign or TNCremo software for PCs.

**TeleService (accessory)**

PC software for remote diagnostics, remote monitoring, and remote operation of the control. For more information, please ask for the Remote Diagnosis with TeleService Technical Information sheet.

**Single station license**
- ID 340449-xx

**Network license**
- For 14 workstations ID 340454-xx
- For 20 workstations ID 340455-xx

**Bus diagnosis**

In Diagnosis mode, the structure of the connected bus systems as well as the details of the connected components can be displayed in a clearly laid out screen.
TNCtest

Acceptance tests on machine tools with external or integrated functional safety (FS) must be conducted reproducibly and verifiably.

The TNCtest and TestDesign program packages can be used to plan and perform acceptance tests for machine tools with HEIDENHAIN controls. The acceptance tests are planned with TestDesign and run with TNCtest.

The TNCtest programs are designed to provide support during acceptance testing, provide required information, and perform automatic configurations, as well as record data and evaluate the data semiautomatically. A tester must evaluate manually whether a test case passed or failed.

TNCAnalyzer

The TNCanalyzer application from HEIDENHAIN provides for simple and intuitive evaluation of service files and log files.

Function:
- Loading of service and log files
- Analysis of temporal sequences and static states
- Filters and search functions
- Data export (HEILogger, CSV and JSON formats)
- Definition of application-specific analysis profiles
- Preconfigured analysis profiles
- Graphic display of signals via TNCscope
- Interaction with other tools that are intended for the display of special sections of the service file
Integrated PLC

Overview
The PLC program is created by the machine manufacturer either at the control (through an external PC keyboard with USB connection) or with the PLC development software PLCdesign (accessory). Machine-specific functions are activated and monitored via the PLC inputs/outputs. The number of PLC inputs/outputs required depends on the complexity of the machine.

PLC inputs/outputs
PLC inputs and outputs are available via the external PL 6000 PLC input/output systems or the UEC 11x. The PLC inputs/outputs and the PROFINET IO or PROFIBUS DP-capable I/O system must be configured with the IOconfig PC software.

PLC programming

<table>
<thead>
<tr>
<th>Format</th>
<th>Statement list</th>
</tr>
</thead>
<tbody>
<tr>
<td>Memory</td>
<td>350 MB</td>
</tr>
<tr>
<td>Cycle time</td>
<td>9 ms to 30 ms (adjustable)</td>
</tr>
</tbody>
</table>

Command set
- Bit, byte, and word commands
- Logical operations
- Arithmetic commands
- Comparisons
- Bracketed terms
- Jump commands
- Subprograms
- Stack operations
- Submit programs
- Timers
- Counters
- Comments
- PLC modules
- Strings

Encryption of PLC data
The encrypted PLC partition (PLCE:) provides the machine tool builder with a tool for preventing third parties from viewing or changing files.

The files on the PLCE partition can be read only by the control itself or by using the correct OEM keyword. This ensures that proprietary know-how and special customer-specific solutions cannot be copied or changed.

The machine tool builder can also determine the size of the encrypted partition. This is not determined until the machine tool builder creates the PLCE partition. Another advantage is that, in spite of the encryption, the data can backed up from the control to a separate data medium (USB drive, network, e.g. through TNCremo) and later restored. You need not enter the password, but the data cannot be read until the keyword is supplied.
PLC window

The TNC 620 can display PLC error messages in the dialog line during operation.

Small PLC window

The TNC 620 can show additional PLC messages and bar diagrams in the small PLC window.

PLC soft keys

The machine manufacturer can display his own PLC soft keys in the vertical soft-key row on the screen.

PLC positioning

All closed-loop axes can also be positioned via the PLC. PLC positioning of the NC axes cannot be superimposed on NC positioning.

PLC axes

Axes can be defined as PLC axes. They are programmed by means of M functions or OEM cycles. The PLC axes are positioned independently of the NC axes.

PLCdesign (accessory)

PC software for PLC program development. The PC program PLCdesign can be used for easy creation of PLC programs. Extensive examples of PLC programs are included with the product.

Functions:
- Easy-to-use text editor
- Menu-guided operation
- Programming of symbolic operands
- Modular programming techniques
- “Compiling” and “linking” of PLC source files
- Operand commenting, creation of the documentation file
- Comprehensive help system
- Data transfer between the PC and control
- Creation of PLC soft keys
Python OEM Process
(option 46)

The Python OEM Process option is an effective tool for the machine tool builder to use an object-oriented high-level programming language in the control (PLC). Python is an easy-to-learn script language that supports the use of all necessary high-level language elements.

Python OEM Process can be used universally for machine functions and complex calculations, as well as to display special user interfaces. User-specific or machine-specific solutions can be efficiently implemented. Numerous libraries on the basis of Python and GTK are available, regardless of whether you want to create special algorithms for special functions, or separate solutions such as an interface for machine maintenance software.

The applications you create can be included via the PLC in the familiar PLC windows, or they can be displayed in separate free windows that can be expanded to the control’s full screen size.

Simple Python scripts (e.g., for display masks) can also be executed without enabling Python OEM Process (software option 46). For this function, 10 MB of dedicated memory is reserved. For more information, refer to the Python in HEIDENHAIN Controls Technical Manual.
The PLC basic program serves as a basis for adapting the control to the requirements of the respective machine. It can be downloaded from the Internet.

These essential functions are covered by the PLC basic program:

**Axes**
- Control of analog and digital axes
- Axes with clamping mode
- Axes with central drive
- Axes with Hirth grid
- Synchronized axes
- 3-D head with C-axis mode
- Reference run, reference end position
- Axis lubrication

**Spindles**
- Control and orientation of the spindles
- Spindle clamping
- Alternative double-spindle operation
- Parallel spindle operation
- Conventional 2-stage gear system
- Wye/delta connection switchover (static, dynamic)

**Tool changers**
- Manual tool changer
- Tool changer with pick-up system
- Tool changer with dual gripper
- Tool changer with positively driven gripper
- Rotating tool magazine with closed-loop axis
- Rotating tool magazine with controlled axis
- Servicing functions for the tool changer
- Python tool management

**Pallet changers**
- Translational pallet changer
- Rotatory pallet changer
- Servicing functions for the pallet changer

**Safety functions**
- Emergency stop test (EN 13849-1)
- Brake test (EN 13849-1)
- Repeated switch-on test for new generation of handwheel

**General functions**
- Feed rate control
- Control of the coolant system (internal, external, air)
- Temperature compensation
- Activation of tool-specific torque monitoring
- Hydraulic control
- Chip conveyor
- Indexing fixture
- Touch probes
- PLC support for handwheels
- Control of doors
- Handling of M functions
- PLC log
- Display and management of PLC error messages
- Diagnostics screen (Python)
- Python example applications
- Status display in the small PLC window
Interfacing to the machine

**OEM cycles (option 19)**

The machine tool builder can create and store his own cycles for recurring machining tasks. These OEM cycles are used in the same way as standard HEIDENHAIN cycles.

**CycleDesign (accessory)**

The soft-key structure for the cycles is managed using the CycleDesign PC program. In addition, CycleDesign can be used to store help graphics and soft keys in BMP format in the TNC. Graphic files can be compressed to ZIP format to reduce the amount of memory used.

**Tool management**

With integral PLC, the tool changer is moved either via proximity switch or as a controlled axis. Tool management including tool life monitoring and replacement tool monitoring is carried out by the TNC 620.

**Tool calibration (option 17)**

Tool touch probes can be measured and checked with the TT tool touch probe system (accessory). Standard cycles for automatic tool measurement are available in the control. The control calculates the probing feed rate and the optimal spindle speed. The measured data are stored in a tool table.

**Touch-probe configuration (option 17)**

All touch-probe data can be configured conveniently through a table. All HEIDENHAIN touch probe systems are preconfigured and can be selected through a drop-down menu.

**Pallet management (option 22)**

Pallet feeding can be controlled via PLC axes. The user defines the pallet sequence, pallet presets, and workpiece presets in the pallet tables. The pallet tables are freely configurable; any information can be stored in the tables and called via the PLC.
# Data transfer and communication

## Data interfaces

<table>
<thead>
<tr>
<th>Overview</th>
<th>The TNC 620 is connected to PCs, networks, and other data storage devices via data interfaces.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ethernet</td>
<td>The TNC 620 can be interconnected via the Ethernet interface. For connection to the data network, the control features a 1000BASE-T (twisted pair Ethernet) connection. Maximum transmission distance: Unshielded: 100 m Shielded: 400 m</td>
</tr>
<tr>
<td>Protocol</td>
<td>The TNC 620 communicates using the TCP/IP protocol.</td>
</tr>
<tr>
<td>Network connection</td>
<td>• NFS file server • Windows networks (SMB)</td>
</tr>
<tr>
<td>Data transmission speed</td>
<td>Approx. 400 to 800 Mbps (depending on file type and network utilization)</td>
</tr>
<tr>
<td>RS-232-C/V24</td>
<td>Data interface according to DIN 66 020 or EIA standard RS-232-C. Maximum transmission distance: 20 m</td>
</tr>
<tr>
<td>Data transmission speed</td>
<td>115 200; 57 600; 38 400; 19 200; 9 600; 4 800; 2 400; 1 200; 600; 300; 150, 110 bps</td>
</tr>
<tr>
<td>Protocols</td>
<td>The TNC 620 can transfer data using various protocols.</td>
</tr>
<tr>
<td>Standard data transmission</td>
<td>The data is transferred character by character. The number of data bits, stop bits, the handshake, and character parity must be set by the user.</td>
</tr>
<tr>
<td>Blockwise data transfer</td>
<td>The data is transferred blockwise. A block check character (BCC) is used for data backup. This method improves data security.</td>
</tr>
<tr>
<td>LSV2</td>
<td>Bidirectional transfer of commands and data as per DIN 66 019. The data is divided into telegrams (blocks) and transmitted.</td>
</tr>
<tr>
<td>USB</td>
<td>The TNC 620 features USB ports for the connection of standard USB devices, such as a mouse, drives, etc. On the back panel of the MC 8xxx and MC 6xxx there are four USB 3.0 ports. One of them leads to the TE, where a cover cap protects it from contamination. More USB 2.0 ports are in the integrated USB hub on the rear of the BF. The USB ports are rated for a maximum of 0.5 A.</td>
</tr>
<tr>
<td>USB cables</td>
<td>Cable length of up 5 m ID 354770-xx Cable length of 6 m to 30 m with integrated amplifier; limited to USB 1.1 ID 624775-xx</td>
</tr>
</tbody>
</table>
USB hub

If you need further USB ports or if the supply current is not sufficient, a USB hub is required. The USB hub from HEIDENHAIN offers four free USB 2.0 ports.

**USB hub**

ID 582884-xx

Power supply: DC 24 V/max. 300 mA

Cover

The USB hub can be installed in the operating panel in such a way that two USB ports can be accessed from the outside. An optionally available cover cap can be used to protect the ports from contamination.

**Cover**

ID 508921-xx

Software for data transfer

We recommend using HEIDENHAIN software to transfer files between the TNC 620 and a PC.

**TNCremo (accessory)**

This PC software package helps the user to transfer data from the PC to the control. The software transfers data blockwise with block check characters (BCC).

Functions:
- Data transfer (also blockwise)
- Remote control (only serial)
- File management and data backup of the control
- Reading out the log
- Print-out of screen contents
- Text editor
- Managing more than one machine

**TNCremoPlus (accessory)**

In addition to the features already familiar from TNCremo, TNCremoPlus can also transfer the current content of the control’s screen to the PC (live screen). This makes it very simple to monitor the machine.

Additional functions:
- Interrogation of DNC data (NC uptime, machine uptime, machine running time, spindle running time, pending errors, data from the data servers—e.g., symbolic PLC operands)
- Targeted overwriting of tool data using the values of a tool presetter

**TNCremoPlus**

ID 340447-xx
Connected Machining

Overview

Connected Machining makes uniformly digital job management possible in networked manufacturing. You also profit from:
- Easy data usage
- Time-saving procedures
- Transparent processes

Remote Desktop Manager (option 133)

Remote control and display of external computers over an Ethernet connection (e.g., Windows PC). The information is displayed on the control’s screen. Remote Desktop Manager allows you to access important applications, such as CAD/CAM applications or order management, from the control.

Remote Desktop Manager ID 894423-xx

HEIDENHAIN DNC (option 18)

The development environments on Windows operating systems are particularly well suited as flexible platforms for application development in order to handle the increasingly complex requirements of the machine’s environment.

The flexibility of the PC software and the large selection of ready-to-use software components and standard tools in the development environment enable you to develop PC applications of great use to your customers in a very short time, for example:
- Error reporting systems that, for example, send the customer a text message to his cell phone reporting problems on the currently running machining process
- Standard or customer-specific PC software that decidedly increases process reliability and equipment availability
- Software solutions controlling the processes of manufacturing systems
- Information exchange with job management software

The HEIDENHAIN DNC software interface is an attractive communication platform for this purpose. It provides all the data and configuration capabilities needed for these processes so that an external PC application can evaluate data from the control and, if required, influence the manufacturing process.

RemoTools SDK (accessory)

To enable you to use HEIDENHAIN DNC effectively, HEIDENHAIN offers the RemoTools SDK development package. It contains the COM component and the ActiveX control for integration of the DNC functions in development environments.

RemoTools SDK ID 340442-xx

For more information, refer to the HEIDENHAIN DNC brochure.
Mounting information
Clearances and mounting

Proper minimum clearance
When mounting the control components, please observe proper minimum clearances and space requirements, as well as length and position of the connecting cables.

Mounting and electrical installation
Observe the following points during mounting and electrical connection:
• National regulations for low-voltage installations at the operating site of the machine or components
• National regulations regarding interference and noise immunity at the operating site of the machine or components
• National regulations regarding electrical safety and operating conditions at the operating site of the machine or components
• Specifications for the installation position
• Specifications of the Technical Manual

Degrees of protection
The following components fulfill the requirements for IP54 (dust protection and splash-proof protection):
• Display unit (when properly installed)
• Keyboard unit (when properly installed)
• Machine operating panel (when properly installed)
• Handwheel

All electric and electronic control components must be installed in an environment (e.g., electrical cabinet, housing) that fulfills the requirements of protection class IP54 (dust and splash-proof protection) in order to fulfill the requirements of pollution degree 2. All components of the OEM operating panel must also comply with protection class IP54, just like the HEIDENHAIN operating panel components.
<table>
<thead>
<tr>
<th><strong>Electromagnetic compatibility</strong></th>
<th>Protect your equipment from interference by observing the rules and recommendations specified in the Technical Manual.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Intended place of operation</td>
<td>This unit fulfills the requirements for EN 50370-1 and is intended for operation in industrially zoned areas.</td>
</tr>
<tr>
<td>Likely sources of interference</td>
<td>Interference is produced by capacitive and inductive coupling into electrical conductors or into device connections, caused by, e.g.:</td>
</tr>
<tr>
<td></td>
<td>• Strong magnetic fields from transformers or electric motors</td>
</tr>
<tr>
<td></td>
<td>• Relays, contactors, and solenoid valves</td>
</tr>
<tr>
<td></td>
<td>• High-frequency equipment, pulse equipment, and stray magnetic fields from switch-mode power supplies</td>
</tr>
<tr>
<td></td>
<td>• Power lines and leads to the above equipment</td>
</tr>
<tr>
<td>Protective measures</td>
<td>• Ensure that the MC, CC, and signal lines are at least 20 cm away from interfering devices</td>
</tr>
<tr>
<td></td>
<td>• Ensure that the MC, CC, and signal lines are at least 10 cm away from cables carrying interfering signals</td>
</tr>
<tr>
<td></td>
<td>• Shielding according to EN 50178</td>
</tr>
<tr>
<td></td>
<td>• Use equipotential bonding lines according to the grounding plan. Please refer to the Technical Manual of your control</td>
</tr>
<tr>
<td></td>
<td>• Use only genuine HEIDENHAIN cables and connecting elements</td>
</tr>
<tr>
<td>Installation elevation</td>
<td>The maximum altitude for installation of HEIDENHAIN control components (MC, CC, PLB, MB, TE, BF, IPC, etc.) is 3000 m above sea level.</td>
</tr>
</tbody>
</table>
Overall dimensions
Main computer

MC 8410

Tolerancing ISO 8016
ISO 2768 - m H
< 6 mm: ±0.2 mm

Ø 5.5

= Front panel opening
= Mounting surface
= Space for air circulation
IPC 6641

Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm
Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm

mm
Controller unit

CC 6106

Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm

mm
UEC 111, UEC 112, UEC 113

mm
Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm
UMC 111 FS
Operating panel, screen, and keyboard

ITC 755

- Front panel opening
- Mounting surface
- Space for air circulation

93
ITC 750

Front panel opening
Mounting surface
Space for air circulation

Symbol meanings:
⊙ = Front panel opening
⊙ = Mounting surface
⊙ = Space for air circulation

Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm

Dimensions are in mm.
TE 720, TE 730

TE 720 B: Without touchpad
TE 730 B: With touchpad

Front panel opening
Mounting surface

= Front panel opening
= Mounting surface

Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm
TE 735

mm

Tolerancing ISO 8015

ISO 2768 - m H

< 6 mm: ±0.2 mm

Front panel opening

Mounting surface

⊙ = Front panel opening

⊙ = Mounting surface
MB 721

= Front panel opening
= Mounting surface

Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm
Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm
PLC inputs and outputs

PL 6000 (PLB 62xx, PLB 61xx)

Clearance for air circulation

mm

Tolerancing ISO 8015
ISO 2768 - m +
< 6 mm: ±0.2 mm
Power supply units

PSL 130

Tolerancing ISO 8015
ISO 2768 - m
< 6 mm: ±0.2 mm

Dimensions in mm:

- Width: 300+1 mm
- Height: 280+1 mm
- Depth: 234.9 mm
- Hole diameter: Ø 12 mm
- Screw size: M5

Additional notes:
- Dimensions are subject to tolerances as specified.
- The diagram includes notes for installation and connection requirements.
Electronic handwheels

HR 510, HR 510 FS

HR 520, HR 520 FS
Holder for HR 520, HR 520 FS

HR 550 FS
HRA 551 FS

Tolerancing ISO 8015
ISO 2768 - m H
≤ 6 mm: ±0.2 mm

mm

122
68.6
48.6

120
83±0.2

210
204
192±0.2
180

8
6
12

320
32

116

32

121

83±0.2

204

8

164

116

32

121

180

320

32
HR 130, HR 150 with control knob

Tolerancing ISO 8015
ISO 2768 = m H
< 6 mm: ±0.2 mm

mm

Ø 38.8
Ø 10.97
Ø 6
Ø 5.6
Ø 5.8
20±0.5
36.7±0.5
10
4.4

M3 x 5
3x
Ø 0.25 C

SW 2
10
4
3x

Ø 10H7
17.7
10
6
22
2

SW 5.5
12
M3
12
M3
7
6

70
Adapter cable for handwheels (straight)

Mounting opening for wall thickness $S = 4$ or more

HR/HRA adapter cable to MC (straight connector)
Adapter cable for handwheels (angled)

Adapter cable for HR/HRA to MC (angled connector)
Interface accessories

Line-drop compensator for encoders with EnDat interface

USB hub

= Mounting surface
USB extension cable with hubs

mm

Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm

L

1000...5000
n x 5000
5000

USB-A

USB-B

n = 0 ... 4
L = Ordering length

KTY adapter connector

mm

Tolerancing ISO 8015
ISO 2768 - m H
< 6 mm: ±0.2 mm

Leave space for connecting cable!
## General information

### Documentation

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<th>Technical documentation</th>
<th>TNC 620 Technical Manual</th>
<th>ID 1098899-xx; in PDF format on HESIS-Web including Filebase</th>
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<tr>
<td></td>
<td>PNC 610 Technical Manual</td>
<td>ID 1191125-xx; in PDF format on HESIS-Web including Filebase</td>
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<td></td>
<td>Inverter Systems and Motors Technical Manual</td>
<td>ID 208962-xx; in PDF format on HESIS-Web including Filebase</td>
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<td>Functional Safety FS Technical Manual</td>
<td>ID 749363-xx; in PDF format on HESIS-Web including Filebase</td>
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<td>TS 260 Mounting Instructions</td>
<td>ID 808652-9x</td>
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<td>TS 460 Mounting Instructions</td>
<td>ID 808653-9x</td>
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<td>TS 740 Mounting Instructions</td>
<td>ID 623761-9x</td>
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<td></td>
<td>TT 160 Mounting Instructions</td>
<td>ID 808654-xx</td>
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<td>TT 460 Mounting Instructions</td>
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<th>TNC 620 HEIDENHAIN Klartext Programming User’s Manual</th>
<th>ID 1096883-xx</th>
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<td>Cycle Programming User’s Manual</td>
<td>ID 1096886-xx</td>
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<th>Miscellaneous</th>
<th>TNCremo User’s Manual As integrated help</th>
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<td>TNCremoPlus User’s Manual As integrated help</td>
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<td>PLCdesign User’s Manual As integrated help</td>
</tr>
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<td>CycleDesign User’s Manual As integrated help</td>
</tr>
<tr>
<td></td>
<td>I0config User’s Manual As integrated help</td>
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<td>KinematicsDesign User’s Manual As integrated help</td>
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<tr>
<th>Other documentation</th>
<th>TNC 620 Touch Probes brochure</th>
<th>ID 896140-xx</th>
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<tr>
<td></td>
<td>Inverter Systems brochure</td>
<td>ID 622420-xx</td>
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<td>Motors brochure</td>
<td>ID 208893-xx</td>
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<tr>
<td></td>
<td>RemoTools SDK virtualTNC brochure</td>
<td>ID 628968-xx</td>
</tr>
<tr>
<td></td>
<td>Remote Diagnosis with TeleService Product Overview</td>
<td>ID 349236-xx</td>
</tr>
<tr>
<td></td>
<td>Touch Probes DVD</td>
<td>ID 344353-xx</td>
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<td></td>
<td>Programming station DVD; TNC 320, TNC 620 demo version</td>
<td>ID 741708-xx</td>
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<tr>
<td></td>
<td>HR 550FS Product Information document</td>
<td>PDF</td>
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<tr>
<td></td>
<td>Safety-Related Control Technology</td>
<td>PDF</td>
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<tr>
<td></td>
<td>Safety-Related Position Measuring Systems</td>
<td>PDF</td>
</tr>
<tr>
<td></td>
<td>Uniformly Digital</td>
<td>PDF</td>
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| Safety parameters       | For HEIDENHAIN products (such as control components, encoders, or motors), the safety characteristics (such as failure rates or statements on fault exclusion) are available on product-specific request from your HEIDENHAIN contact person. |

| Basic circuit diagram   | More information on basic circuit diagrams can be requested from your HEIDENHAIN contact person. |
Service and training

Technical support
HEIDENHAIN offers the machine manufacturer technical support to optimize the adaptation of the control to the machine, including on-site support.

Exchange control
In the event of a malfunction, HEIDENHAIN guarantees the timely shipment of an exchange control (usually within 24 hours in Europe).

Helpline
Our service engineers are available by phone if you have any questions regarding adaptation or malfunctions:

NC support
+49 8669 31-3101
E-mail: service.nc-support@heidenhain.de

PLC programming
+49 8669 31-3102
E-mail: service.plc@heidenhain.de

NC programming
+49 8669 31-3103
E-mail: service.nc-pgm@heidenhain.de

Encoders / machine calibration
+49 8669 31-3104
E-mail: service.ms-support@heidenhain.de

APP programming
+49 8669 31-3106
E-mail: service.app@heidenhain.de

If you have questions about repairs, spare parts, or exchange units, please contact our Service department:

Customer service, Germany
+49 8669 31-3121
E-mail: service.order@heidenhain.de

Customer service, international
+49 8669 31-3123
E-mail: service.order@heidenhain.de

Machine calibration
On request, HEIDENHAIN engineers will calibrate your machine’s geometry (e.g., with a KGM grid encoder).

Technical courses
HEIDENHAIN provides technical customer training in the following subjects:

- NC programming
- PLC programming
- TNC optimization
- TNC servicing
- Encoder servicing
- Special training for specific customers

For more information on dates or registration:

<table>
<thead>
<tr>
<th>Technical training courses in Germany</th>
<th>+49 8669 31-3049</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>E-Mail: <a href="mailto:mtt@heidenhain.de">mtt@heidenhain.de</a></td>
</tr>
</tbody>
</table>

| Technical training courses outside of Germany | www.heidenhain.de EN » Company » Contact » HEIDENHAIN worldwide |
Other HEIDENHAIN controls

Examples

MANUALplus 620

Information: MANUALplus 620 brochure

- Compact contouring control for CNC and cycle lathes
- Axes: Max. 10 control loops, of which up to 6 are configurable as spindles
- Suitable for horizontal and vertical lathes as well as vertical boring and turning mills
- Up to 3 principal axes (X, Z, and Y), B axis, closed-loop spindle and counter spindle, C1/C2 axis, and driven tools
- Up to 3 programmable auxiliary axes (U, V, W) for control of steady rest, tailstock, and counter spindle
- The position of a parallel secondary axis can be shown combined with its principal axis
- Compact design: Screen and main computer in one unit
- For operation with HEIDENHAIN inverter systems and preferably with HEIDENHAIN motors
- Uniformly digital with HSCI interface and EnDat interface
- 15.6-inch multi-touch display with 1366 × 768 pixels
- Integration of the keyboard on the right side of the display
- Installation dimensions of MC 8420T compatible to MC 7 410T
- Storage medium: CFR CompactFlash memory card (CFast) with 8 GB
- Programming of turning, drilling, and milling operations with smart.Turn, according to DIN or via cycles
- TURN PLUS for automated smart.Turn program generation
- ICP free contour programming for turning and milling contours
- For simple tool holders (multifix), tool turrets, or tool magazines
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